# SUPPRESSION OF COMBUSTION OSCILLATIONS WITH MECHANICAL DAMPING DEVICES INTERIM REPORT



Prepared Under Contract NAS8-21310 For

George C. Marshall Space Flight Center National Aeronautics And Space Administration Huntsville, Alabama



BOX 2691, WEST PALM BEACH, FLORIDA 33402



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#### FOREWORD

This report describes the work performed during the period 27 June 1968 to 16 June 1969 under Contract NASS-21310 for the NASA Marshall Space Flight Center. The NASA Technical Monitor was Mr. C.R. Bailey, and Dr. Uno Ingard of the Massachusetts Institute of Technology served as technical consultant. Special acknowledgement is given to C.R. Bailey for suggesting the possible correlation between acoustic resistance and aperture flow coefficients, and to Senior Experimental Engineer J.A. Lipsit of Pratt & Whitney Aircraft for his help in the development of the electronic system for the pressure-phase impedance measuring apparatus used on this program.

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## NOMENCLATURE

SYMBOL

#### DESCRIPTION

A	Maximum Pressure Amplitude
	Cross Sectional Area of Cavity
A <sub>c</sub> A <sub>2</sub>	Area of Apertures
c	Sonic Velocity
C <sub>f</sub>	Flow Coefficient Defined as C <sub>d</sub> . C <sub>v</sub>
C <sup>D</sup>	Discharge Coefficient
C <sub>c</sub>	Coefficient of Contraction
d	Aperture Diameter
f	Frequency
g	Gravitational Constant
I <sub>i</sub>	Incident Intensity
I <sub>t</sub>	Transmitted Intensity
k	Wave Length constant = $\omega$ /c
K	Resistance Coefficient = $R/\rho u$
к <sub>1</sub>	Resistance Coefficient = RC <sub>f</sub> / <b>p</b> u
K <sub>2</sub>	Resistance Coefficient = $RC_f^2/\rho u$
L	Backing Distance
М	Mach Number
$^{\mathrm{M}}\mathbf{p}$	Mach Number of Flow Past Apertures
M <sub>T</sub>	Mach Number of Net Flow Through Apertures
$\ell_{ t eff}$	Effective Aperture Length
P <sub>1</sub>	Total Pressure in Front of Sample
$P_2$	Total Pressure in Resonator Cavity
P	Incident Pressure
p	Static Pressure
R	Acoustic Resistance
$R_{f}$	Time Independent Resistance
r <sub>w</sub>	Chamber Radius
t	Sample Thickness
u	Peak Particle Velocity
u <sub>m</sub>	Mean Particle Velocity

## NOMENCLATURE (Continued)

SYMBOL	DESCRIPTION
V <sub>p</sub>	Velocity of Flow Past Apertures
v <sub>c</sub>	Cavity Volume
v <sub>T</sub>	Velocity of Net Flow Through Apertures
w	Mass Flowrate
X	Acoustic Reactance
χ	Specific Acoustic Reactance = $\chi/\sigma\rho$ c
Y	Expansion Coefficient Accounting for Compressible Flow Effects
Z	Specific Acoustic Impedance
$z_p$	Specific Acoustic Impedance of an Orifice
α	Absorption Coefficient
β	Diameter Ratio
$oldsymbol{ heta}$	Specific Acoustic Resistance = $R/\sigma \rho c$
$\theta_{ extsf{V}}$	Specific Acoustic Resistance with Flow
$\theta_1$	Resistance at Fundamental Frequency with Increased Sound Level at First Harmonic
$\Delta_{ m n} \ell^{/ m d}$	Nonlinear Correction Term
•	Nonlinear Correction Factor = $(\Delta_n l/d) + 1$
€ <sub>C</sub>	Nonlinear Corrector Factor Corrected for $C_{f f}$
€ <sub>E</sub>	Experimental Nonlinear Correction Factor
μ	Dynamic Viscosity
ν	Kinematic Viscosity
φ	Phase Angle
ρ	Density
σ	Open Area Ratio
$\sigma_{\!\!1}$	Function for High Open Area Ratios = $\sigma/1$ - $\sigma^2$
ω	Angular Frequency
γ	Ratio of Specific Heats

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#### NOMENCLATURE (Continued)

### SYMBOL DESCRIPTION Flow Through Coefficient Defined as $R/\rho V_{_{T\!T}}$ λ Coefficient Defined As $RC_{f}^{2}/\rho_{V_{T}}$ Coefficient Defined As $RC_f^{\frac{3}{2}}/\rho V_T$ $au_2$ ξ Angular Position General Subscripts Denotes Conditions at Resonance NFDenotes No Net Flow Upstream of Sample 1 2 Downstream of Sample Ε Experimental Т Theoretical

### Superscript

- Denotes Time Varying Quantity

With Net Flow

# SECTION I OBJECTIVE OF PROGRAM

The objectives of the work performed during the first year of effort under Contract NAS8-21310 were (1) to improve the present acoustic liner design theory in the high frequency and high sound pressure regime, and (2) to develop and demonstrate, using a cold-flow acoustic device, the techniques required for the measurement of absorbing liner acoustical characteristics during hot firings of rocket chambers. To meet these objectives, three tasks were defined, as described below.

### A. TASK I - HIGH FREQUENCY ANALYSIS

Conduct experimental investigations using an existing standing wave impedance measuring device at frequencies up to 8000 Hz and at sound pressure levels to approximately 160 decibels (db)\* and use the data, obtained by the pressure ratio-phase angle method, to provide the basis for a new or an improved absorbing liner design theory. In addition, obtain sufficient data at frequencies lower than 2000 Hz for comparison with standard ASTM impedance tube data.

#### B. TASK II - CHAMBER SIMULATOR FABRICATION

Fabricate a cylindrical cold-flow test apparatus for the purpose of obtaining resonator impedance data in a simulated rocket thrust chamber. The chamber to be equipped with a high-intensity sound generator capable of exciting a tangential mode of instability. The capability for gas flow through and past the resonators to be provided. Sound pressure level capability to be at least 160 db with frequencies to approximately 2000 Hz.

#### C. TASK III - SIMULATOR EXPERIMENTS

Conduct tests to determine any differences in the performance of resonator arrays between standing wave impedance tube data and tangential wave data obtained during tests of the apparatus fabricated under Task II. It was expected that this series of testing would develop the techniques and give a preliminary definition of the limitations of absorber impedance measurement during thrust chamber firings.

<sup>\*</sup>In this report, all pressures expressed in db are based on a reference pressure of 0.0002 microbar.

# SECTION II SUMMARY OF ACCOMPLISHMENTS

Under Task I, 23 resonator assemblies (samples) were used in an existing high-frequency impedance measuring device to supply data for analysis. More than 300 data points were obtained at sound pressures up to 176 db. Analysis of the resistance data revealed the existence of significant sample-to-sample differences that were found to be caused by minute nonuniformities in the aperture edges. Excellent correlation of resistance data was obtained using a time independent flow coefficient as a measure of the edge effects. An equation expressing the functional relationship between resistance, particle velocity, density, and flow coefficient was formulated from an analogy with time-independent flow. The agreement of reactance data with experiment was found to be good, but some improvement through the use of a simple expression for the effective aperture length was noted. Comparisons of nonlinear correction factors computed from the high-frequency data were made with those obtained using ASTM probe-type impedance tubes by correlating the correction factors with sound pressure level. Agreement was found to be only fair with a considerable amount of scatter in the factors computed from the new data. The scatter was attritubed to both aperture edge effects and to the extremely wide range of geometric variables and conditions over which the experiments were conducted. No attempts to improve the correlation between the new factors and SPL were made because the correct proportionality between resistance and particle velocity is not expressed by the equation from which the correction factor is defined.

Under Task II, a static (no flow) chamber simulator was used to provide preliminary acoustic data on which the design of flow-type apparatus could be based. From the results of the preliminary experiments, it was shown that with a partitioned liner, the effects of incidence angle were negligible; therefore, either normal or tangential standing wave impedance measuring devices could be employed for the simulator flow experiments. The existing high-frequency impedance tube was modified for testing with flow through the apertures, and a new tube was designed for the experiments with flow past the apertures.

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Simulator experiments (Task III) with flow past or with flow through the apertures showed that the empirical theory derived from probe-type impedance tubes predicted effects of flow on resistance to be significantly greater than that measured using the pressure-phase impedance measuring techniques. Reasons for the observed differences are believed to be caused by limitations and inaccuracies inherent to the probe-type impedance device when used with net flows. New empirical correlations, based on the simulator data, were formulated for use in liner design analyses.

From the results of the work reported herein, it is recommended that the following equations be used in the analytical design of absorbing liners; an example of one way in which the equations may be applied is presented in Appendix A.

Acoustic resistance with no net flow in the nonlinear regime characterized by particle velocities  $\geq 60$  ft/sec:

$$R = 0.37 \, \rho_{\rm u}(c_{\rm f})^{-2} \tag{II-1}$$

or

$$\theta = 0.37 \text{ u/C}_{f}^{2} \text{ c} \sigma_{1}$$
 (II-2)

For velocities less than 60 ft/sec

$$R = (8\omega\rho\mu)^{1/2} (1 + t/d)$$
 (II-3)

is a reasonable approximation; however, some uncertainty still exists as to how aperture edge effects should be considered at lower particle velocities. It is therefore recommended that further analysis be conducted in an attempt to improve the theory for use in the transition and linear regimes.

The acoustic reactance of a partitioned cavity of backing depth smaller than quarter wave length can be computed for a conventional resonator array with cavity cross-sectional area approximately equal to facing surface area from

$$\chi = \frac{\ell_{\text{eff}\omega}}{c\sigma} - \frac{c}{L\omega} \tag{II-4}$$

where

$$\ell_{eff} = t + d.$$
 (II-5)

For situations with flow through or past the apertures the following should be used:

Flow through the apertures:

$$\theta = \frac{M_{\rm T}}{c_{\rm f}^3} \sigma_1 \text{ where } M_{\rm T} \ge 0.5 M_{\rm NF}$$
 (II-6)

If the net flow through the apertures is less than 0.5  $M_{\rm NF}$ , then equation (II-2) should be used. The reactance for any flow-through velocity is computed from equations (II-4) and (II-5).

Flow past the apertures:

$$\theta = \theta_{NF} (1 + 1.9 M_p)$$
 (II-7)

where  $\theta_{
m NF}$  is the resistance calculated from equation (II-2), i.e., for no zero net flow. The equation

$$\ell_{\text{eff}} = (t + d)(1 - 1.65 \,\text{M}_{\text{p}})$$
 (II-8)

should be used to calculate the effective length and then used in equation (II-4) to compute the reactance with flow past the apertures.

It is recommended that further experiments be conducted to better define the effect of higher, i.e., greater than a Mach number of 0.26, gas flow past on the acoustic characteristic of a resonator. The experiments should be conducted with media of different density to determine if the flow effects are dependent upon velocity or Mach number and with samples of various thickness, open area ratio, backing cavity depth, and aperture diameter.

The extrapolation of the liner design theory, based on the results of cold-flow experiments to hot-firing conditions, introduces significant uncertainties, primarily because the magnitude of pressure oscillations, particle velocities, and gas flow can only be approached in cold-flow simulations. In the past, it has been necessary to assume that the

<sup>\*</sup>From the results of previous experiments (Reference 2), it was found that, for liners subjected to simulataneous flow through and past the apertures, the acoustic resistance should be computed as if only flow through were present.

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results from the cold-flow experiments would be applicable to hot-firing situations principally because no reliable experimental techniques for making similar measurements during firings were known. Efforts under the present program have shown the pressure-phase impedance measuring technique to be an extremely precise experimental tool that can be readily adapted to hot-firing experiments. It is, therefore, recommended that such experiments be conducted for the purpose of verifying and improving, if necessary, the above design theory. Finally, it is also suggested that attempts be undertaken to improve the absorbing liner design theory for unpartitioned liners.

# SECTION III TASK I - HIGH FREQUENCY ANALYSIS

The absorption coefficient used in the analytical design of acoustic liners is computed from

$$a = \frac{4\theta}{(\theta+1)^2 + \chi^2} \tag{III-1}$$

where  $\theta$  is the specific acoustic resistance and X is the specific acoustic reactance of the resonator arrays. At frequencies near resonance where most liners are designed to operate, the resistance is much greater than the reactance  $(\theta >> X)$ ; thus, the resistance is the controlling factor in predicting the absorption of the liner.

For sound intensities of less than 100 db, where viscous drag caused by the oscillatory flow of gas through the apertures is the principal mechanism for energy loss, the resistance can be determined with sufficient accuracy using existing theory. But as the intensity is increased, extreme turbulence and circulatory flow patterns develop in the apertures, causing the resistance to become a nonlinear function of sound pressure. The resistance in this nonlinear regime cannot be predicted from theoretical considerations; therefore, designers must rely on experimental data for use in their analyses.

As first suggested by Ingard (Reference 1), the data are usually correlated in the form of an "end correction" factor,  $\Delta_n \ell$ , which must be added to the viscous resistance in the following manner:

$$\theta = \frac{(8\mu\rho\omega)^{1/2}}{\rho c\sigma} (1 + t/d + \Delta_n I/d)$$
 (III-2)

Until recently, the generation of high intensity sound in a controlled experiment was difficult; thus, only limited amounts of correction factor data for arrays of resonators were available. In 1967, as part of the final year of effort under Contract NAS8-11038, a conventional ASTM impedance tube with a high intensity electropneumatic sound generator was used to measure the resistance of three different resonator arrays ( $\sigma = 3$ , 5, and 10%) over a frequency range of 400 to 2000 Hz. Correction factors, computed from the data using equation (III-2), were correlated with sound pressure, as shown in figure III-1.

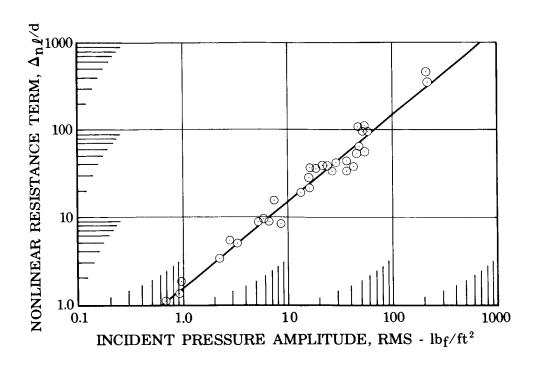


Figure III-1. Nonlinear Resistance Data

FD 19156

Although the ASTM impedance tube is a useful apparatus for measuring absorption coefficients, it does have an inherent limitation, i.e., precise, high-frequency (above 2000 Hz) impedence data are difficult to obtain, especially with sound levels above 140 db. In an attempt to overcome this limitation, a pressure-phase impedance measuring device was fabricated and a series of preliminary experiments were conducted in which the absorption coefficients of several resonator arrays were measured at frequencies from 1000 to 8000 Hz (Reference 2). Comparison of results with absorption coefficients computed using the correction factors of figure III-1 showed that the coefficients could be accurately predicted up to a frequency slightly greater than that of resonance, but, at higher frequencies, the measured absorption coefficients were significantly lower than the computed values. (See figure III-2.) From these results, it was concluded that the use of the correction factor data in the acoustical regime characterized by high sound pressures and high frequencies was not valid, and it was recommended that the analysis of high-frequency impedance characteristics be continued as part of the present program.

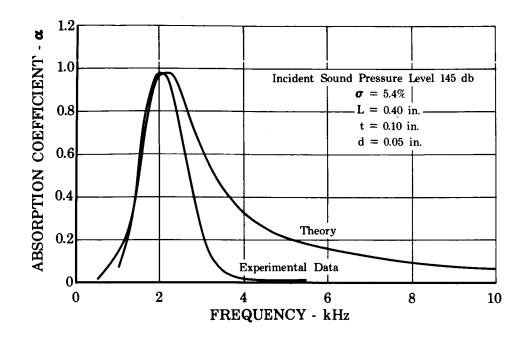


Figure III-2. High Frequency Data Comparison

FD 31427A

#### A. EXPERIMENTS

To determine the relationship between the resonator configuration and its acoustical characteristics, each of the 23 resonator assemblies described in table III-1 was installed in the impedance apparatus described in Appendix B and tested over a range of frequencies and sound pressure levels. Over 300 data points were obtained, each consisting of a measurement of the cavity sound pressure and the phase angle for a set frequency and total sound pressure, i.e., the sound pressure in front of the resonator face. The range of frequencies and sound pressures was 700 to 5800 Hz and 140 to 176 db, respectively. The data from a series of experiments with one resonator at a constant sound level of 160 db are illustrated in figure III-3 to show how the cavity phase angle and sound pressure vary with frequency.

Table III-1. Resonator Configurations Used in Impedance Experiments

Resonator Sample No.	Open Area Ratio, %	Sample Thickness, in.	Cavity Backing Depth, in.	Aperture Diameter, in.
1	1.50	0.10	0.50	0.047
2	3.00	0.10	0.50	0.056
2 3	3.95	0.09	0.50	0.052
4	5.40	0.10	0.50	0.052
5	5.65	0.09	0.50	0.047
6	6.90	0.10	0.50	0.052
7	8.00	0.10	0.50	0.056
8	8.85	0.10	0.50	0.047
9	10.80	0.10	0.50	0.052
10	13.00	0.10	0.50	0.052
11	5.40	0.05	0.50	0.052
12	5.40	0.15	0.50	0.052
13	5.40	0.20	0.50	0.052
14	5.40	0.25	0.50	0.052
15	13.00	0.10	0.15	0.052
16	10.80	0.10	0.20	0.052
17	10.80	0.10	0.15	0.052
18	5.40	0.10	0.50	0.037
19	5.40	0.10	0.50	0.094
20	5.40	0.10	0.40	0.052
21	5.40	0.10	0.60	0.052
22	8.0	0.10	0.40	0.056
23	8.0	0.10	0.60	0.056

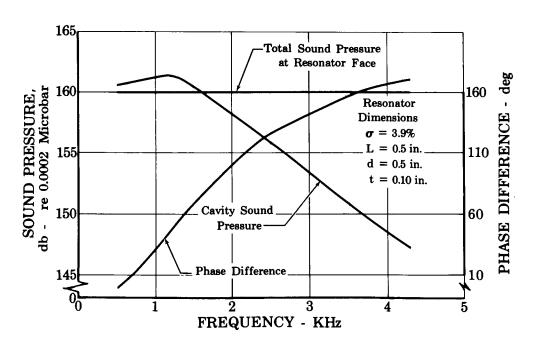


Figure III-3. High Frequency Data for a Particular Resonator Assembly

FD 31349A

#### B. ANALYSIS OF DATA

The equations derived in Appendix B were programmed for a digital computer and were used to determine the components of impedance, absorption coefficients, incident sound pressures, and orifice velocities from the pressure-phase data; results are included in Appendix D. The computations were made for every data point, however, not all of the data were used in the following analysis. An error analysis of this experiment (see Appendix B) showed that significant errors can be introduced at certain phase angles and, if the total resonator impedance fell below 0.5, therefore, such data were excluded.

#### 1. Acoustic Resistance Data

Originally, two approaches were to be taken in the analysis of the acoustic resistance data: nonlinear correction terms were to be computed and correlations similar to that of figure III-1 were to be attempted. The other approach was to be based on observations published by Ingard and Ising (Reference 3). A discussion of results from the latter approach is presented first.

In their work, Ingard and Ising used a hot-wire annemometer to measure the oscillatory flow velocity, u, in a single orifice mounted at the end of a tube. A piston driven at a frequency of 150 Hz was used to generate sound pressures up to 162 db. Using their data, the researchers showed that when the orifice velocity was greater than approximately 30 ft/sec, the driving sound pressure was approximately equal to  $\rho u^2$ . In addition, in the nonlinear regime, when the resistance was significantly greater than the orifice reactance, they found that,

 $R \simeq \rho u$ 

and confirmed that the relation was frequency-independent, at least up to a frequency at which the orifice reactance equals the resistance. (Note, however, that even though the function  $R = \rho u$  is independent of frequency per se, the resistance will vary with frequency because the particle velocity for a particular resonator varies with frequency.) Such a simple expression for the acoustic resistance would be extremely useful for acoustic liner design purposes; therefore, attempts to

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develop a similar function from the high-frequency resonator data were begun.

The resonator array with an open area ratio of 1.5% was most like the single orifice used by Ingard and Ising that had a  $\sigma$  of 0.5%; thus, the data from that array were compared with their annemometer data. Also included in the comparison were the earlier ASTM impedance tube data of Bies and Wilson (Reference 4) and Ingard's data of 1953 (Reference 1). As shown in figure III-4, excellent agreement among all of the data samples was found.

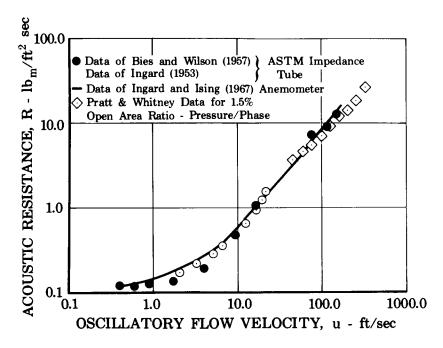


Figure III-4. Comparison of Pressure-Phase
Data With ASTM Impedance Tube
Data and Anemometer Data

FD 33034

Shown in figures III-5 and III-6 are the results of similar comparisons of the resistance data obtained from resonators with open area ratios greater than 1.5%. The resistance for each particular facing sample was found to be directly proportional to the orifice particle velocity, but in every case the resistance fell lower than the line representing the function  $R = \rho u$ . In addition, significant sample-to-sample differences in the data from each resonator were evident.

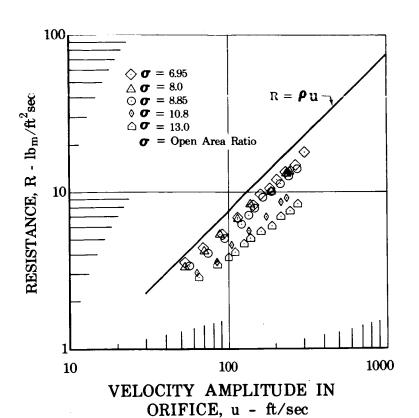
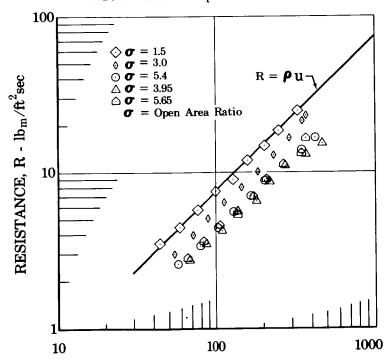


Figure III-5. Resistance Data for Low Open Area Liner Samples

FD 27990A



VELOCITY AMPLITUDE IN ORIFICE, u - ft/sec
Figure III-6. Resistance Data for High Open

FD 29159A

As an aid in further investigation of the sample-to-sample differences in resistance, a coefficient of proportionality, K, defined as the ratio of resistance to the product of particle velocity and density, i.e.,  $K = R/\rho u, \text{ was computed for each data point. Correlation of the proportionality coefficient with open area ratio and facing thickness was attempted, as shown in figures III-7 and III-8, but no creditable functional relationship between K and either geometric variable could be established.$ 

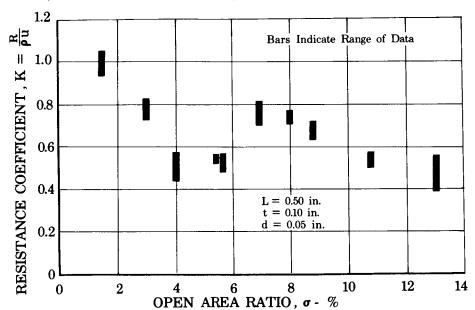


Figure III-7. Proportionality Coefficient FD 29162 for Resonators of Various Open Area Ratios

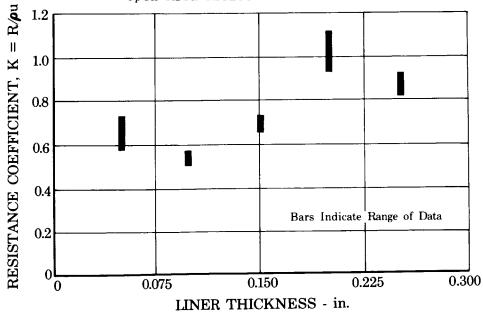


Figure III-8. Effect of Sample Thickness on Acoustic Resistance Proportionality Coefficient

FD 29157

#### a. Spectrum Analyses

A possible cause of the variation in the resistance data was considered to be the harmonics of the fundamental frequency that might be present in the impedance apparatus and resonator cavity. Even though all harmonics are electronically filtered before the sound pressures were recorded, it was not known what effect superimposed harmonics might have on the orifice velocity. If the effect were to increase the velocity without changing the resistance, the value of K could be significantly affected. To investigate this possibility, additional high-frequency experiments were conducted. For the experiments, two of the sound sources were connected to a separate oscillator and amplifier so that sound waves at two different frequencies could be introduced. First, spectrum analyses were made with the 5.4 and 8.0% open area ratio samples installed in the impedance tube. As shown in figure III-9, sound pressures with frequencies corresponding to the first four harmonics were detected with both resonator assemblies. In neither case were pressures at frequencies lower than that of the fundamental found in the impedance tube or resonator cavity.

The fundamental frequency was next introduced at a level of 135 db using two drivers, and the resulting basepoint sound level was measured at the first harmonic. Then through the use of two additional drivers, the sound pressure at the first harmonic was increased in 5-db increments until it exceeded the 135 db level at the fundamental by 15 db. The ratio of the resistance at the fundamental frequency to the basepoint resistance at the same frequency is shown in figure III-10 as a function of the harmonic sound level. The results show that the resistance at the fundamental frequency is not affected until the sound level at the first harmonic exceeds that at the fundamental by 10 db or more. The results of the above spectrum analysis showed that the amplitude of all natural harmonics were lower than that of the fundamental; therefore, the effect of harmonics were eliminated as a possible cause of the sample-to-sample differences in the resistance data.

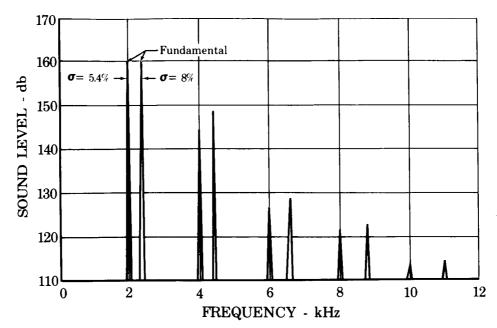


Figure III-9. Results of Spectrum Analysis for 5.4 and 8% Open Area Samples

FD 29158

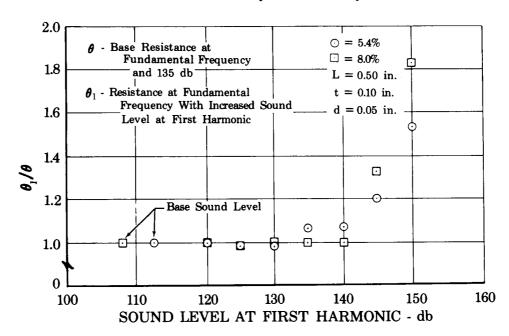


Figure III-10. Effects of Pressure Oscillations FD 29160 at First Harmonic on Resistance at Fundamental Frequency

#### b. Flow Coefficient Effects

It has long been known that the acoustic impedance of resonators operating in the nonlinear regime is strongly affected by the circulatory flow patterns that develop in the vicinity of the orifice. In 1950,

Ingard and Labate (Reference 5), using stroboscopic illumination of smoke particles, investigated the acoustical streaming around resonator orifices. Circulatory flow patterns were analyzed as a function of the oscillatory particle velocity through the orifice and the various types of circulation were classified into the four following regions:

- Region 1. A low sound region with stationary circulation; the flow is directed out from the orifice along the axis
- Region 2. A region of stationary circulation in which the direction of flow along the axis is toward the orifice, i.e., the reverse of that in Region 1
- Region 3. A medium sound intensity region where pulsatory effects are superimposed on circulation of the kind in Region 2
- Region 4. A high sound intensity region in which pulsatory effects are predominant, resulting in the formation of jets and vortex rings: the jet consists of a strong airflow through the orifice, signified by a sudden burst of air; this burst appears symmetrically on both sides of the orifice and is made up of pulses contributed by each cycle of the sound wave.

In all of the experiments reported herein, the sound levels were high enough to cause the type of circulation patterns of Regions 3 and 4, i.e., regions of extreme turbulence characterized by pulsatory jets. Highly turbulent time-independent flow through orifices is known to be significantly affected by slight (or even minute) changes in the orifice edge shape, e.g., a square-edged orifice has a higher resistance to flow than an orifice of identical diameter but with a slightly rounded leading edge.

With time-independent flow, a measure of edge effects is obtained through the use of a flow coefficient in the equations relating flow-rate to pressure differential,  $(\Delta P)$ , i.e.,

$$w = A_2 c_f Y_1 \sqrt{\frac{2g\rho\Delta_r^P}{1 - (\beta)^4}}$$
 (III-3)

where  $C_{\hat{f}}$  is a single flow coefficient consisting of the product of the contraction coefficient and the discharge coefficient. This flow coefficient was experimentally determined with time-independent flow\* for

<sup>\*</sup>Refer to Appendix C for a description of flow coefficient experiments.

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several resonator facing samples of identical open area ratio and aperture diameter for which the acoustic resistance had been previously measured.

Correlation of the inverse of the flow coefficient with the acoustic resistance coefficient, shown in figure III-11, revealed similar trends in both sets of data and indicated that further analysis was warranted.

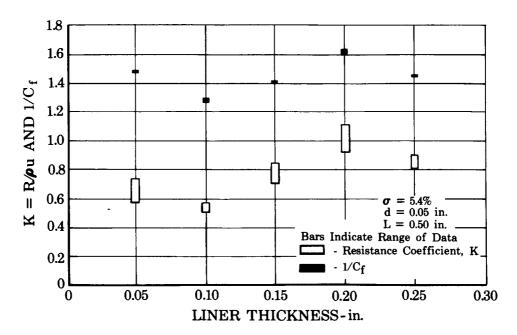


Figure III-11. Comparison of Flow and Resistance FD 29161 Coefficients

Flow coefficients of the remaining facing samples were measured, and, in an attempt to determine the functional relationship between the two coefficients, the following flow-acoustic analogy was investigated.

The definition of the acoustic impedance of an orifice

$$Z_{p} = R + iX = \frac{\overline{P}_{1} - \overline{P}_{2}}{\overline{u}}$$
 (III-4)

may, for the nonlinear regime where  $R \gg X$ , be written as simply

$$R \simeq \frac{\overline{P}_1 - \overline{P}_2}{-} \tag{III-5}$$

For time-independent flow through an orifice, the analogous flow resistance parameter is defined as

$$R_{f} = \frac{P_{1} - P_{2}}{u_{m}} \tag{III-6}$$

where  $P_1$  -  $P_2$  is the pressure differential and  $u_m$  is the mean velocity in the orifice. The orifice equation for imcompressible flow and neglible approach factor

$$u_{m} = C_{f} \sqrt{2g (P_{1} - P_{2})/\rho}$$
 (III-7)

may be rewritten as

$$\frac{P_1 - P_2}{u_m} = \frac{\rho u_m}{2g (C_f)^2}$$
 (III-8)

Using equations (III-6) and (III-8), the following proportionality is established.

$$R_{f}^{\alpha} \frac{\rho_{u_{m}}}{(C_{f})^{2}}$$
 (III-9)

The similarity in the acoustic and flow resistance parameters and the known dependence of the flow resistance upon the flow coefficient,  $\mathbf{C}_{\mathbf{f}}$ , suggests that if the flow coefficient is to be correlated with acoustic resistance data, the most suitable functional relationship should be of the form,

$$R = R \left( \rho, u, C_f^{-2} \right)$$
 (III-10)

Correlation of the resistance data with the flow coefficient using the data from all facing samples was attempted. A mean value of the proportionality coefficient, K, was determined from the resistance data of each sample, and, in addition, two new proportionality coefficients defined as

$$K_1 = \frac{R}{\rho_{11}} C_f \tag{III-11}$$

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$$K_2 = \frac{R}{\rho u} (C_f)^2 \qquad (III-12)$$

were computed. It is worthy of note that  $K_2$  is written in the same terms as those of equation (III-10). The results are shown in figure III-12.

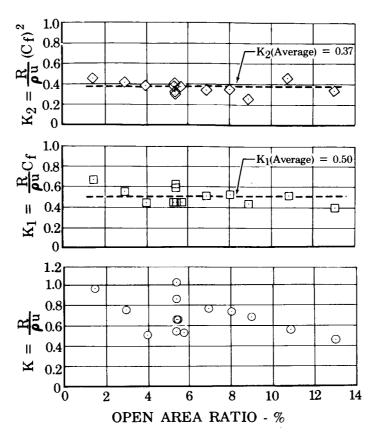


Figure III-12. Effect of Facing Flow Coefficient FD 29171 on Acoustic Resistance

It is evident that the sample-to-sample differences in the  $\rm K_1$  and  $\rm K_2$  values are significantly less than the original K values; the differences in  $\rm K_2$  appear to be somewhat less than those of  $\rm K_1$ , which is substantiated by comparing the deviations in the  $\rm K_1$  and  $\rm K_2$  values, as follows

Coefficient	Average Value	Average Deviation, %	Maximum Deviation, %
к <sub>1</sub>	0.50	13.4	34
K <sub>2</sub>	0.37	12.5	32

From the results, it is concluded that the most precise representation

of the acoustic resistance data in the nonlinear regime is

$$R = 0.37 \ \rho u C_f^{-2} \tag{III-13}$$

It is interesting to note that a sharp-edged orifice like that used by Ingard and Ising (Reference 3) is known to have a flow coefficient of approximately 0.61. If that value is used in equation (III-13)

$$R = \frac{0.37}{(0.61)^2} \rho u = 1.0 \rho u$$
 (III-14)

further corroboration of the validity of equation (III-13) is obtained.

Equation (III-13) is only valid for use in the nonlinear regime, thus the particle velocity at which the transition from the linear to the nonlinear regime occurs must be known. To define the velocity additional data were taken using six resonator assemblies over a range of velocities from 5 to 400 ft/sec. As shown in figure III-13 the data were correlated in the form  $RC_f^2$  as a function of particle velocity. From these results the particle velocity that separates the nonlinear regime from the transition and linear regimes was arbitrarily chosen to be 60 ft/sec.

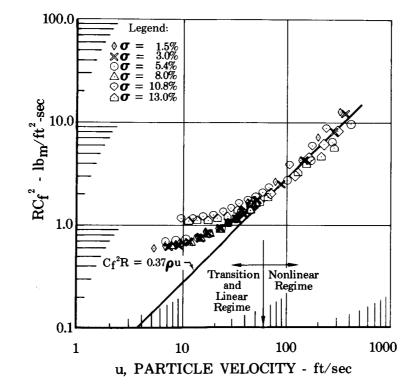


Figure III-13. Correlation of Resistance Data
In the Transition and Nonlinear
Acoustic Regimes

FD 31421

#### c. Nonlinear Correction Factors

A second approach in the analysis of the resistance data involved the nonlinear correction factors commonly used for design purposes. The factors were computed from the data using equation (III-2), i.e.,

$$\Delta_{\rm n} \ell / d = \frac{\theta \rho c \sigma}{(8\mu\rho\omega)^{1/2}} - 1 - t/d$$
 (III-15)

where  $\theta$  is the experimental specific acoustic resistance. Results are shown in figure III-14; also shown are lines representing correction factors from the ASTM impedance tube experiments (Reference 2) and the original correlations of Ingard (Reference 1) and Blackman (Reference 6). Agreement between the impedance tube correction factors and those from the pressure phase experiments is as good as can be expected in view of the amount of scatter in the new data. The scatter can be attributed to both aperture edge effects and to the extremely wide range of geometric variables and conditions over which the experiments were conducted. No attempts to improve the correlation between the new factors and SPL were made due to the fact that a simple relation between incident SPL and  $\Delta_n \ell/d$  is only valid for  $f \leq f_0$  because the correct proportionality between resistance and particle velocity at frequencies greater than resonance is not expressed by the equation from which the correction factor is "defined" (equation III-2).

θ **∝**f 1/2

which correctly accounts for the decrease in resistance with particle velocity below resonance, but which produces an increasing error as frequency is increased above resonance. The situation can be corrected by rewriting equation (III-2) so that the correct functional relationship between resistance and all frequencies is established. To do so, however, only leads to an unnecessary complication, because the true variable affecting resistance is velocity not frequency.

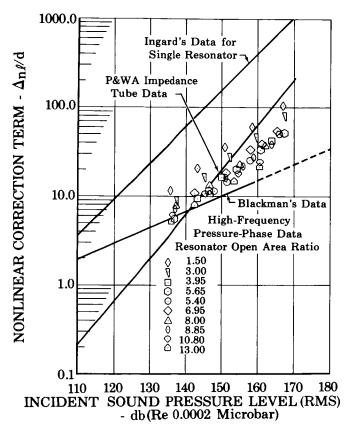


Figure III-14. Comparison of Nonlinear Correction Factors From High Frequency
Experiments With Results From
Impedance Tube Experiments

Expressing the correction factor as a function of particle velocity has been attempted by Ingard (Reference 1), Blackman (Reference 6), Sirignano (Reference 7), and others; however, Ingard's and Blackman's corroboration with resonator array experiments has been rather poor.

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The theory of Sirignano is unique in that he has corrected the defined  $\Delta_{\rm n}$  to account not only for the incorrect frequency relation but also for the density and viscosity so that the proper functional relation for resistance in the nonlinear regime is obtained. This may be shown by the following.

Sirignano's theory states

$$\epsilon = \frac{\mathbf{u}}{3\pi} \sqrt{\frac{2\rho}{\omega\mu}} \tag{III-16}$$

where

$$\epsilon = (\Delta_{n} \rho/d) + 1 \tag{III-17}$$

If equation (III-2) is written in the following form

$$R = \theta \rho c \sigma = (8 \mu \rho \omega)^{1/2} (1 + t/d + \Delta_n \ell/d)$$
 (III-18)

and equation (III-16) is substituted, then

$$R = (8\mu\rho\omega)^{1/2} (t/d + \epsilon)$$
 (III-19)

In the nonlinear regime  $\epsilon >> t/d$  is a reasonable assumption; hence, it can be neglected in the above equation. Replacing  $\epsilon$  by equation (III-16) and simplifying produces

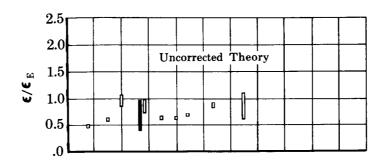
$$R = \frac{4\rho u}{3\pi} = 0.43\rho u \tag{III-20}$$

which shows that even though Sirignano's defined nonlinear correction term, equation (III-16), is a function of both frequency and viscosity, when the term is used with equation (III-19) to compute the acoustic resistance the two variables cancel so that the resulting expression, equation (III-20), is correctly independent of both. However, comparison of equation (III-20) with equation (III-13) suggests that the Sirignano theory will not account for aperture edge effects and if the theory is modified by the flow coefficient to account for these effects in the following manner:

$$\epsilon_{\rm C} = \epsilon_{\rm C} c_{\rm f}^{-2} \tag{III-21}$$

then the values of  $\epsilon_{\rm C}$  will be, on the average, approximately 16% higher than experimental data.

To check the hypothesis, a comparison of the correction factor data with equation (III-16) was made. The results are shown in figure III-15 as the ratio of  $\epsilon$  / $\epsilon$ <sub>E</sub> where  $\epsilon$ <sub>E</sub> is the value of ( $\Delta$ <sub>n</sub> $\ell$ /d + 1) computed from the resistance data (again using equation (III-15) and  $\epsilon$  is computed using equation (III-16). As expected the resulting sample-to-sample differences appear similar to those found to be caused by aperture edge effects. (See figures III-7 and III-8.)



■ Data From Variable Sample Thickness Experiments

Data From Variable Open Area Ratio Experiments

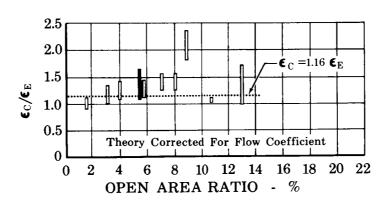


Figure III-15. Comparisons of Experimental Non- FD 31420 linear Resistance Correction Factors With Theory of Sirignano

To correct for the edge effects the theoretical values of  $\epsilon$  were multiplied by the value of  $C_f^{-2}$  for each facing sample; results are also shown in figure III-15, as a ratio of  $\epsilon_C^{/\epsilon}$  where  $\epsilon_C$  is the corrected value.

A decrease in sample-to-sample differences is observed, and a line representing a 16% difference between theory and experiment in figure III-15 may be noted to pass through most of the data. The variation with  $\sigma$  should not be mistaken as a possible result of variations in the thickness-to-diameter ratio; this ratio was essentially constant ( $\approx$  2) for all but the shaded bar.

#### 2. Acoustic Reactance Data

From the analysis of the nonlinear regime reactance data, it was found that the present theory is in good agreement with experiment; however, improvement was obtained by using a new simple expression for the effective aperture length. No aperture edge effects in the reactance data were noted and no improvement in the theory through the use of the flow coefficient could be obtained. A summary of this work, including the most significant results, are described in the following paragraphs.

To show a comparison of the reactance data with theory, the results from experiments with apertures of various thickness were used. The theoretical reactance was determined from the equation

$$\chi = \frac{2\pi}{c} \frac{\ell_{\text{eff}}}{\sigma} f - \frac{c}{2\pi} \frac{1}{L} \frac{1}{f}$$
 (III-22)

where the term containing  $\ell_{\rm eff}$  is the inertance, and the term containing L is the capacitance. The effective aperture length was determined from the equation

$$\ell_{\text{eff}} = t + 0.85 \text{ d} (1 - 0.7\sqrt{\sigma}).$$
 (III-23)

The experimental values of inertance, reactance, and effective length were determined using the pressure-phase data, as shown in Appendix B.

Only a comparison of the inertance data (figure III-16) need be made because the capacitance is an exact term. The agreement at high frequencies is of the same degree as at the low frequencies. Apparently, there is no need to improve the method of predicting inertance at high frequencies; however, the theory could be improved for better agreement at all frequencies by improving the expression for effective length. Additional analysis of the data with this objective was attempted.

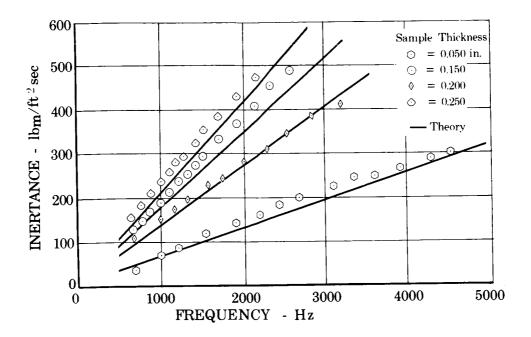


Figure III-16. Comparison of Inertance Data FD 29173A With Present Theory

Analysis of a large sample of effective length data led to the conclusion that the best representation for the effective length is simply

$$\ell_{\text{eff}} = t + d$$
 (III-24)

where t is the resonator facing thickness and d is the aperture diameter. The error in the use of the equation is demonstrated in figure III-17. It is worthy to note that except for the data from one particular facing, the maximum error is less than  $\pm$  20%. The use of equation (III-24) to predict the frequency of resonance

$$f_{o} = \frac{c}{2\pi} \sqrt{\frac{\sigma}{L \ell_{eff}}}$$
 (III-25)

will result in a much smaller error in  $f_0$  because  $\ell_{\rm eff}$  appears to the -1/2 power. The improvement in agreement between inertance data and theory using equation (III-24) may be noted by comparing figure III-16 with figure III-18.

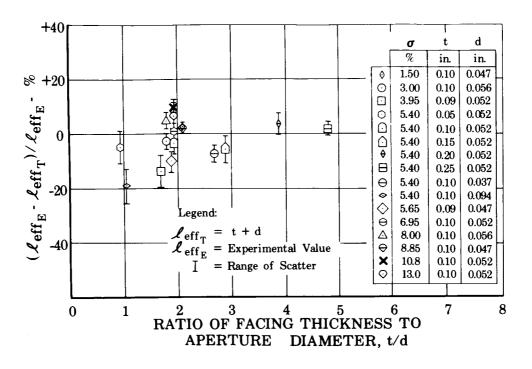


Figure III-17. Error in Theoretical Effective FD 31350 Length Term

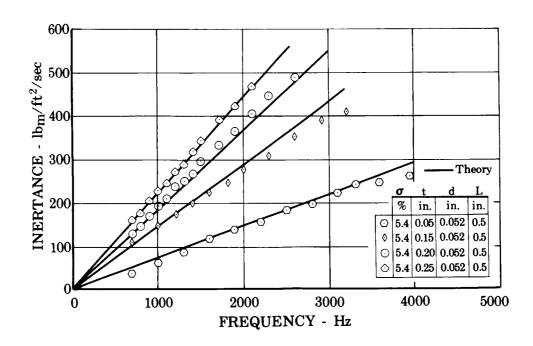


Figure III-18. Comparison of Inertance Data With Improved Theory

FD 31378

## SECTION IV TASK II - CHAMBER SIMULATOR FABRICATION

The objective of the work performed under Task II was the fabrication and preliminary checkout of a cylindrical acoustic device that could be used to provide impedance data for an absorbing liner in a simulated rocket chamber. This type of experiment was necessary for the reason discussed below.

The theory used in the design of absorbing liners utilizes empirical correlations developed from impedance data obtained with ASTM-type impedance tubes. Impedance apparatus of this type use flatplate liner samples rigidly mounted at the end of a tube in which the only organized acoustic modes are longitudinal. In these types of tests both the incident, refracted and reflected waves must be normal to the liner surface; therefore, results obtained applied only to one-dimensional, normal reacting surfaces.

For such surfaces, the refracted pressure wave travels nearly normal to the surface, irrespective of the particular angle of incidence; hence, it is reasonable to assume that the ratio of acoustic pressure acting upon the surface to the fluid velocity normal to the surface will also be independent of the direction of the incident wave. Then the impedance of the surface, which by definition is the above ratio, can be expressed simply as the normal specific acoustic impedance.

Uncertainty in the formulation of the absorbing liner theory is introduced by the assumption that a cylindrical surface has the same acoustic characteristics as a one-dimensional normally reacting surface. To eliminate this uncertainty it was necessary to determine the acoustic characteristics of a cylindrical liner having obliquely incident sound waves and to determine if such a liner is a normally reacting surface.

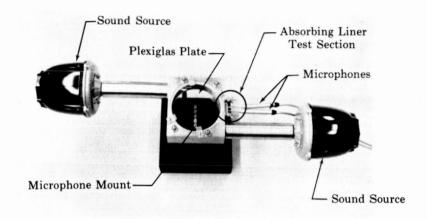
#### A. APPARATUS

No design criteria have been set forth for the design of tangential and radial acoustic chambers; therefore, a static (i.e., without flow capabilities) tangential acoustic chamber was fabricated so that tests could be conducted to provide design information for the chamber simulator. (See figure IV-1.) This information would include the number of acoustic drivers necessary for nonlinear operation, the response characteristics

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of the chamber, and an efficiency evaluation of the coupling device between the drivers and the chamber.



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Figure IV-1. Static Tangential Chamber

FD 25290

The cylindrical test chamber had a 5-in. internal diameter with an axial length of 1 in. The ends of the chamber were made of 1/2-in. Plexiglas plates to enable visual observation of pressure distributions when styrofoam pellets were placed in the test chamber. The top Plexiglas plate contained instrumentation ports for microphones and the plate was capable of being rotated so that any point in the chamber could be observed. Two Atlas Sound Driver Units, Model PD-60T, were used as sound sources; both were tangentially mounted on the test chamber. The liner test section occupied approximately 8% of the total surface area on the outer diameter chamber wall, and was located 45 deg from one of the sound inlets. Two Bruel & Kjaer, Model 4138, 1/8-in. condenser microphones were used in the absorbing liner test section. One microphone measured pressure oscillations in the chamber in front of the test section and the second, pressure oscillations in the resonator cavity. The outputs of both microphones were supplied to the pressure-phase impedance measuring apparatus described in Appendix B.

#### B. PRELIMINARY EXPERIMENTS

Preliminary response tests of the static tangential chamber showed that the first three tangential modes and the first two radial modes

could be excited. The first tangential mode corresponded to a frequency of 1572 Hz with a maximum amplitude of 165 db, well above the linear acoustic regime. The response characteristics of the chamber were good; i.e., no distortion of the standing wave pattern was observed on an oscilloscope used to monitor the output of a microphone, mounted through the Plexiglas endplate 1/2 in. from the outer chamber wall, as the plate and microphone were rotated 360 deg around the chamber.

The chamber simulator was modified to determine if transverse modes could be excited by locating the sound source near the outer edge of the endplate. (See figure IV-2.) The first five tangential modes were excited with maximum sound levels of 170, 172, 166, 161, and 160 db, respectively. Radial modes could not be detected within the chamber. The coupling device between the speakers and the chamber appeared to be better for this configuration because higher sound levels were reached with one sound source as compared to the first configuration which required two sound sources to reach an even lower level at the tangential modes. Another advantage of the second configuration is that the entire tangential standing wave could be rotated in the chamber by rotating the endplate in which the sound source is mounted. This enables the test section to be positioned at any point within the tangential wave, a distinct advantage over the first configuration which maintained a fixed relationship between one point on the standing wave and the test section.

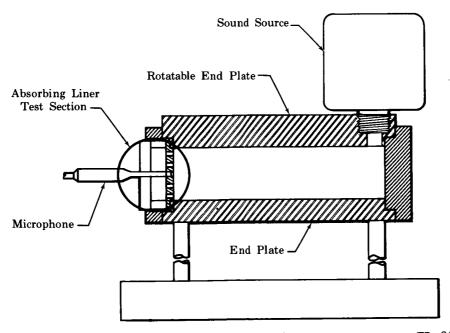


Figure IV-2. Modified Chamber Simulator

A third configuration was tested in which the sound source was located in the center of the Plexiglas endplate. It was found that with this configuration radial modes could be easily generated but no tangential modes could be detected.

It was decided to use the first configuration for additional investigation of transverse modes because either tangential or radial standing waves could be generated within the test chamber. Additional studies were made to better understand the characteristics of the first tangential mode because it is primarily the type of instability encountered in rocket chambers and also because it is believed to be the source of obliquely incident waves.

An experiment was conducted in which a 1/4-in. Bruel & Kjaer condenser microphone was mounted flush with internal side of a Plexiglas endplate at a radius of 2.25 in. The plate was rotated in steps of 10 deg until the microphone made one full revolution around the chamber; at each step the rms sound pressure was recorded. Figure IV-3 shows that, as expected, the standing first tangential wave follows a sinusoidal pattern represented by  $P = A \sin \xi$  where A is the peak amplitude at 90 and 270 deg which corresponded to the center of the two sound source discharge ports.

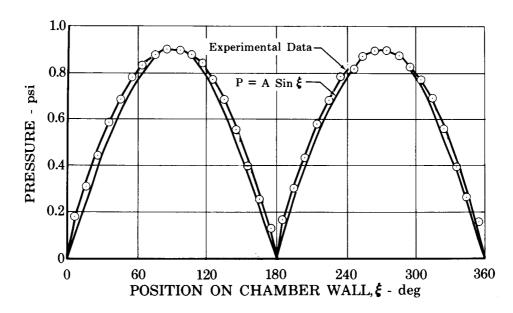


Figure IV-3. First Tangential Pressure Profile FD 31379A

The results of this testing can be used to determine the location and minimum number of pressure transducers necessary to measure the peak amplitude in a thrust chamber with a standing first tangential mode of instability. If only one transducer were used and if it were located so that a nodal point of the first tangential mode occurred at the same point, the instability would not be detected. To determine the minimum number of transducers and the locations that are needed to detect the maximum amplitude of the first tangential mode of instability, two pressure transducers located 90 deg apart can be used to provide data to calculate the peak pressure amplitude. The proof is as follows.

The equations  $P_X = A \sin \xi$  and  $P_Y = A \sin (\xi + 90 \text{ deg}) = \cos (\xi)$  represent the two measured pressures at any position on the circumference of the chamber wall where  $P_X$  and  $P_Y$  are 90 deg apart and A is the peak amplitude. Squaring both equations and adding gives

$$P_{X}^{2} + P_{Y}^{2} = A^{2} (\sin^{2} \xi + \cos^{2} \xi) = A^{2}$$

Solving for A gives

$$A = \sqrt{P_X^2 + P_Y^2}$$
 (IV-1)

Therefore, the peak amplitude of the first transverse mode is easily determined by measuring the pressure at two points in the same cross section, 90 deg apart on the chamber walls. The results of this experiment can also be used to show that if the acoustical characteristics of an absorbing liner are to be measured, the minimum number of transducer pairs (one in the chamber wall and one in the liner cavity) is equal to one plus the mode number of the expected tangential instability.

To determine relationship between obliquely incident sound waves and the acoustic characteristics of a resonator configuration, each of the 5 resonator assemblies described in table IV-1 were installed in the absorbing liner test section (see figure IV-1) of the chamber simulator. The facing sample for each resonator had a curved surface with the same radius as the outer wall of the chamber. (See figure IV-4.) The backing cavity was formed by using Teflon spacer plates that conformed to the contour of the sample when the curved backing wall was secured to the assembly. (See figure IV-5.) In figure IV-5 the back of the liner sample and the

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cavity space with the condenser microphones installed can be seen (a Plexiglas backing wall was used in this assembly for illustration purposes).

Table IV-1. Resonator Configurations Used in Chamber Simulator Impedance Experiments

Resonator Sample No.	Open Area Ratio, %	Sample Thickness, in.	Cavity Backing Depth, in.	Aperture Diameter, in.	Flow Coefficient
1	1.4	0.10	0.3	0.052	0.83
2	3.2	0.10	0.5	0.052	0.78
3	4.7	0.10	0.6	0.052	0.83
4	7.0	0.10	0.5	0.052	0.78
5	9.4	0.10	0.6	0.052	0.78

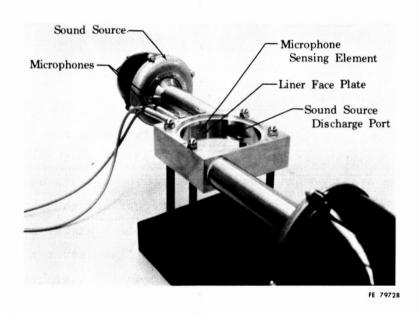
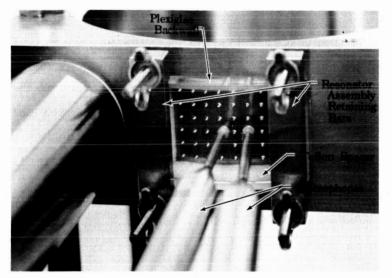


Figure IV-4. Instrumented Chamber Simulator

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Figure IV-5. Illustration of Resonator Cavity FD 31423
And Instrumentation

Data for determining acoustic properties of each resonator configuration was obtained at a frequency of 1572 Hz, which corresponded to the first tangential mode of the chamber, over a range of sound pressures from 135 to 165 db. The data obtained consisted of the measurement of the sound pressures in the chamber at the face of the liner sample and in the resonator cavity, and the phase angle between these two pressure waves.

#### C. ANALYSIS OF DATA

To determine the acoustic characteristics of each resonator assembly the equations derived in Appendix B were used to determine the components of impedance, absorption coefficient, and orifice particle velocities from the pressure-phase data.

#### 1. Acoustic Resistance Data

The results of the high frequency experiments (see Section III) were used to develop an empirical correlation relating acoustic resistance with orifice particle velocity. The data used in that analysis was obtained from one-dimensional normally reacting surfaces with normal incident sound waves. To determine if a cylindrical surface with obliquely incident sound waves is characterized by the same relationship a similar analysis was performed with data obtained from the chamber simulator.

In the analysis of the simulator data the open area ratio  $(\sigma)$  of the sample resonators was defined as

$$\sigma = \frac{A_2 L}{V_C}$$
 (IV-2)

where  ${\bf A}_2$  is the total area of the apertures, and L and  ${\bf V}_{\bf C}$  are the length and volume, respectively, of the backing cavity. This equation must be used in place of the usual definition of  ${\boldsymbol \sigma}$  because the cavity is wedge shaped causing the cross-sectional area to vary across the entire length of the cavity. (In the longitudinal test apparatus the cross-sectional area of the cavity ( ${\bf A}_{\bf C}$ ) is constant , thus the volume can be defined as

$$V_{C} = A_{C}L \qquad (IV-3)$$

which when used in equation (IV-2) gives

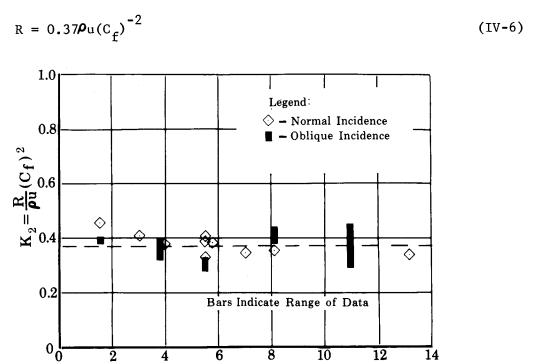
$$\sigma = \frac{A_2}{A_C} \tag{IV-4}$$

the usual definition of  $\sigma$ .) Equation (IV-3) does not apply to the volume of the resonator cavity in the cylindrical chamber, thus, equation (IV-2) must be used to calculate the open area ratio.

Correlation of the acoustic resistance (R) data with the flow coefficient ( $C_f$ ) was made using the function obtained from the high frequency analysis, i.e.,

$$R = \frac{K_2 \rho_u}{(c_f)^2}$$
 (IV-5)

Equation (IV-5) was used to calculate the values of  $\rm K_2$  for all data taken in the tangential tests where the particle velocities were in the nonlinear regime, i.e., greater than 60 ft/sec. A comparison of the results with those of the high frequency analysis are shown in figure IV-6. It is worthy of note that the same average value of  $\rm K_2$ , 0.37, was obtained for both flat and cylindrical surfaces. It is therefore concluded that the nonlinear acoustic resistance for both cases can be represented by the expression



OPEN AREA RATIO-%

Figure IV-6. Comparison of Resistance Coefficient for Normal and Tangential Incidence

FD 31418

#### 2. Acoustic Reactance Data

Comparison of the effective aperture length data from the static simulator experiments with the theory derived from the high-frequency experiments were made. Results are shown in figure IV-7 where the effective length data from the latter experiments have been included. With the exception of the data from one resonator sample ( $\sigma = 3.2\%$ ) the scatter in the data is seen to fall within the range of the high-frequency data. It is not known why the data from the single sample fall lower than

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those of the other samples; however, it is evident that there are no essential differences in the effective length from either the cylindrical or flat facing samples.

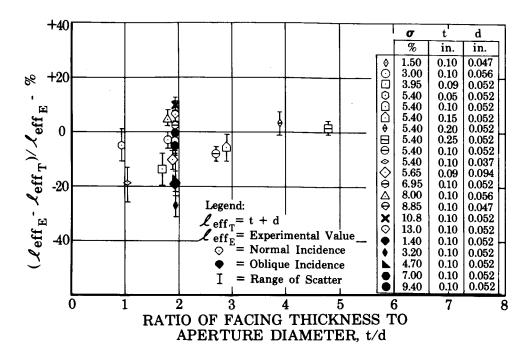


Figure IV-7. Comparison of Effective Length FD 31417
Data With Theory

#### D. CONCLUSIONS AND RECOMMENDATIONS

Results of the chamber simulator experiments show that both one-dimensional and cylindrical liner surfaces are characterized by an identical relationship between the acoustic resistance and particle velocity. In the relationship developed with flat samples the particle velocity was normal to the liner surface, therefore it is only reasonable that the particle velocity is also normal to the surface of a cylindrical liner. Since the ratio of the driving pressure to the particle velocity normal to a surface is defined as the normal specific acoustic impedance then a cylindrical liner with a partitioned cavity having oblique incident sound waves has the same acoustic characteristics as a normally reacting surface.

From the results of the chamber simulator experiments it is concluded that either cylindrical or longitudinal impedance tubes can be used to provide data for the development of empirical correlations to be used in the

design of partitioned absorbing liners for rocket chambers. Absorbing liners used in rocket chambers are often unpartitioned and designed to give maximum absorption at frequencies near that of the first tangential mode. As shown in the preliminary experiments the first tangential mode forms a pressure profile around the chamber wall in the form of a sine wave with resulting severe pressure gradients around the liner facing. In equations used to determine the absorption coefficient of the liner, the impedance of the common backing cavity is based on a theory that assumes a uniform pressure distribution across the liner backing cavity. Analytical attempts have not been successful in developing an expression to describe the pressure distribution and impedance of an unpartitioned cavity with a pressure gradient across the liner surface.

It is recommended that additional research be conducted in an attempt to improve the absorbing liner design theory for unpartitioned liners. Until the theory can be improved it will be necessary to assume that the impedance of an unpartitioned cavity having a pressure gradient across it has the same acoustic characteristics as one which has a uniform pressure distribution.

## SECTION V TASK III - SIMULATOR EXPERIMENTS

Absorbing liners used in rocket engines always have gases flowing past, and, under some circumstances, a simultaneous flow of gases will occur in which the gases flow through, as well as past, the liner apertures. Previous experiments relating the effects of flow have shown wide differences in results. This is seen in the case of a recent publication by Ingard and Ising (Reference 3) in which the effects on the acoustic resistance due to flow through (no flow past) a single orifice were determined with the use of a hot-wire annemometer. A significant difference was found to exist between these results and those previously determined (Reference 2) by use of an ASTM-type impedance tube in which an array of orifices was tested.

In the past, the effects on resistance of flow past the apertures of flat facing samples could only be measured using modified ASTM-type impedance tubes. With such an apparatus a complete resonator assembly could not be used since a flow duct had to be installed in place of the resonator cavity. Hence, the effects on the absorption coefficient and reactance components could not be measured directly. The use of the pressure-phase impedance measuring technique imposes no such limitations and, in addition, permits the use of cylindrical test assemblies. It was originally planned to use a cylindrical test chamber for the flow experiments. Tests made with the static (no flow) chamber simulator (see Section IV) showed that a liner with a cylindrical surface and partitioned cavity is a normally reacting surface in which the effects of incidence angle are negligible. Therefore, the real and imaginary parts of impedance can be measured in either a cylindrical or longitudinal impedance apparatus so long as a uniform pressure distribution is maintained across the liner surface. Thus, for simplicity longitudinal impedance tubes were used in the flow experiments.

The objective of the flow experiments under Task III is to obtain, using the pressure-phase technique, impedance data and absorption coefficients with flow through (no flow past) the apertures and flow past (no flow through) the apertures of absorbing liner assemblies. Where possible, comparisons of the data with the existing empirical flow correlations were to be made to verify and/or improve the existing theory.

#### A. FLOW-THROUGH EXPERIMENTS

The static (no flow) high frequency impedance apparatus described in Appendix B was modified for the flow-through (no flow-past) tests. (See figure V-1.) In the experiment two samples having open area ratios of 3.94 and 10.8%, thickness of 0.10 in., aperture diameter of 0.052 in., and backing cavity depth of 0.5 in. were used. In order to determine the effects of net flow on the acoustic resistance each resonator assembly was tested at a constant frequency near resonance (resistance greater than reactance) and the average flow-through velocity was varied from near zero to 325 ft/sec. The same tests were made at two different sound pressure levels of 145 and 160 db. To determine the effects of flow through the apertures on the absorption coefficient, each resonator assembly was tested at a constant sound level of 160 db over a range of frequencies from 500 to 4000 Hz while the flow-through velocities were held constant at 136, 237, and 302 ft/sec.

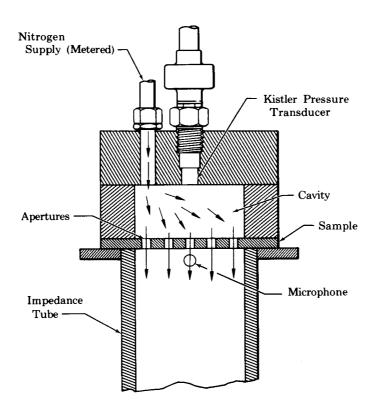


Figure V-1. Sketch of Test Section - Impedance FD 29176A
Measuring Device Used With Flow
Through Apertures

Results of the tests made at constant frequencies are shown in figure V-2, in which the ratio of the acoustic resistance with flow to that with no flow has been correlated with the average flow-through velocity and compared with previous data obtained with the ASTM-type impedance apparatus. The exact causes of the differences between the ASTM data and the pressure-phase data are not known; however, they are believed to be caused by several differences in the test procedures which are explained as follows. In the probe tube type experiments, the sample did not have a backing cavity, thus allowing the incident sound wave to pass through the apertures and out the flow duct instead of interacting in the cavity and reradiating back into the impedance tube as in the pressure-phase experiments. In the ASTM-type experiments, a probe tube was used to investigate the standing wave which is established in the gaseous media having a net flow towards the sample. It is known that this net flow can distort the standing wave pattern thus producing error of unknown magnitude in the data results. Also, based on previous experience with the probe tube investigations of the standing wave pattern, it has been found that precise impedance data for such an experiment are difficult to obtain. It does appear that the pressure-phase data is more accurate, especially because, as shown by results of the high frequency analysis in Section III, they are in good agreement with the hot-wire experiments of Ingard and Ising (Reference 3).

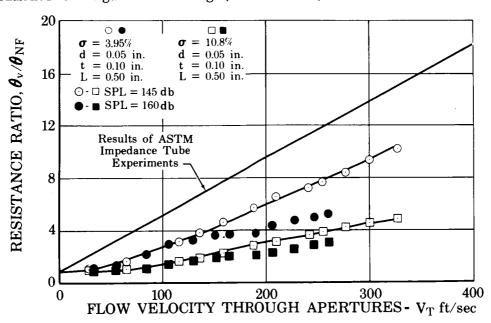


Figure V-2. Comparison of Data from the ASTM and the Pressure-Phase Experiments for Flow-Through Tests

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Investigations of the flow-through data was based upon the results of the high frequency analysis, as explained in Section III, i.e., the resistance is given by the empirical correlation

$$R = \frac{0.37 \rho_{\rm u}}{c_{\rm f}^2} \tag{V-1}$$

and also upon the results of Ingard and Ising (Ref. 3), which suggests that for cases where the steady-flow through velocity  $(\mathbf{V}_{T})$  is greater than the particle velocity with no net flow then the resistance is given by

$$R = \lambda \rho V_{T} \tag{V-2}$$

In equation (V-2)  $\lambda$  is a proportionality constant that Ingard and Ising found to have values between 1 and 1.5.

Combining equation (V-1) and (V-2) shows that the resistance can best be represented by the equation

$$R = \frac{\lambda (0.37) \rho V_{T}}{C_{f}^{2}}$$
 (V-3)

By letting  $\tau = 0.37\lambda$  equation (V-3) becomes

$$R = \frac{\tau \rho V_{T}}{C_{f}^{2}}$$
 (V-4)

where  $\tau$  is an empirical constant that must be experimentally determined. Using equation (V-4) in analyzing the data to determine the value of  $\tau$ , two cases were considered. One in which the steady flow-through velocity was the average velocity (V<sub>T</sub>) and not corrected for the flow coefficient

$$\tau_1 = \frac{RC_f^2}{\rho V_T}$$

and a second one in which the steady flow velocity was corrected for the flow coefficient, i.e., the average velocity is divided by the flow coefficient giving

$$\tau_2 = \frac{RC_f^3}{\rho_{V_T}}$$

The results are shown in figure V-3 in which the constants ( $\tau_1$  and  $\tau_2$ ) have been correlated with the ratio of the steady flow-through velocity to the peak velocity ( $u_{NF}$ ) amplitude with zero net flow. The results show that when the net flow velocity is greater than the one-half of the peak acoustic velocity with no net flow, a good approximation for both  $\tau_1$  and  $\tau_2$  would be unity. In figure V-3, the correlation using  $\tau_2$  is noted to be better than  $\tau_1$ , i.e., less scatter; therefore, it is concluded that the effects of flow-through can best be represented by the following:

$$R = \frac{\rho V_T}{C_f^3} \quad \text{where } V_T > 0.5 \text{ u}_{NF}$$
 (V-5)

where  $V_T$  is the average flow velocity and the term  $C_f^{\ 3}$  is used to account for the aperture edge effects on both the acoustic peak velocity and the net flow velocity.

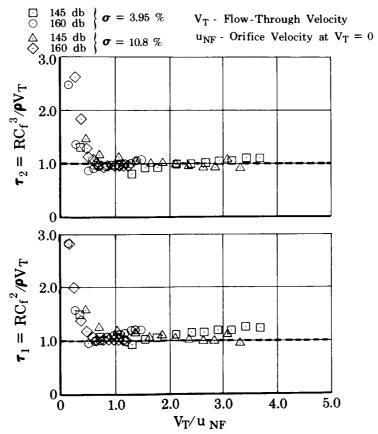


Figure V-3. Correlation of Data for Constant
Frequency Experiments with the Ratio
of the Net Flow-Through Velocity to
the Peak Orifice Velocity for No
Net Flow

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The dimensionless resistance is defined as

$$\theta = \frac{R}{\sigma \theta c} \tag{V-6}$$

therefore, equation (V-5) may be written in the form

$$\theta = \frac{V_{T}}{c_{f}^{3}\sigma_{c}} = \frac{M_{T}}{c_{f}^{3}\sigma} \text{ where } M_{T} > 0.5 M_{NF}$$
 (V-7)

In equation (V-7)  ${\rm M}_{\rm T}^{}$  is the Mach No. of the net flow through the apertures.

Equation (V-5) is seen to be independent of frequency. This means that for a given net flow velocity greater than 0.5 $u_{\rm NF}$ , the resistance of an acoustic liner is independent of frequency; confirmation follows. The results of the constant flow-through experiments with variable frequencies are shown in figure V-4 where the absorption coefficient is correlated with frequency as a function of net flow velocity. In the two cases for net velocities greater than 0.5  $u_{\rm NF}$ , i.e., net velocities of 237 and 302 ft/sec, almost no resonance effects are observed in the absorption curves.

Referring to equation (B-10) in Appendix B, it is clear that if the absorption coefficient is constant over a range of frequencies and if the resistance is much greater than the reactance, as was the case for frequencies greater than 1500 Hz, then the resistance must remain a constant value over the same range of frequencies. Thus the results of the variable frequency tests further substantiate the empirical correlation given in equation (V-5).

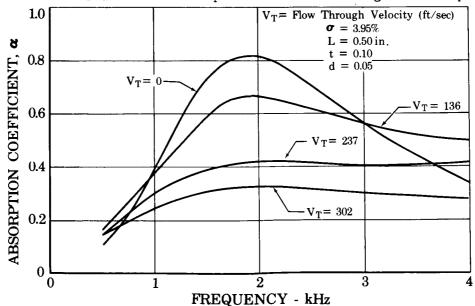


Figure V-4. Summary of Experiments Showing the FD 29165
Effects of Flow-Through the Apertures
on the Absorption Coefficient

It was observed that the effective length decreases with an increase in the net flow-through velocity, however as shown in figure V-5 this was only true for a sound pressure level of 145 db. For a sound pressure level of 160 db which is of more interest for acoustic liner design purposes, the effects of flow through the apertures on effective length, and therefore acoustic reactance, were found to be negligible.

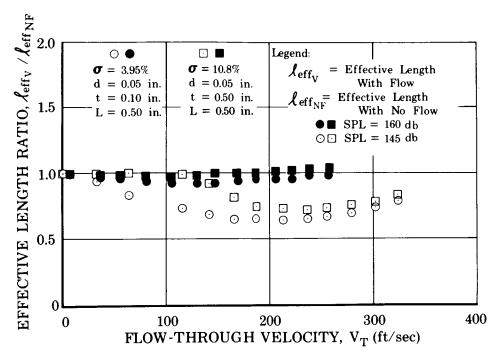


Figure V-5. Effects of Flow Through Apertures FD 31412A on Effective Length

#### B. FLOW-PAST EXPERIMENTS

The cold flow apparatus shown in figure V-6 was fabricated for the flow-past experiments. The apparatus, theoretically capable of producing sound pressure levels in excess of 170 db at frequencies of 100 to 2000 Hz for flows up to 400 fps consists of:

- 1. A Ling 94-B electropneumatic transducer
- 2. An expansion horn
- 3. A 2-in. dia standing wave tube
- 4. A circular absorbing liner test section
- 5. Two Atlantic Research pressure transducers
- 6. A tube extension
- 7. A reflection plate.

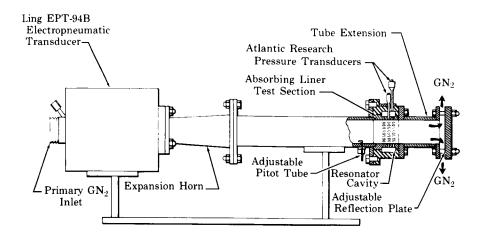


Figure V-6. Flow-Past Apparatus

FD 31411

Briefly, the operation of the apparatus is as follows: sound waves, along with a metered supply of gaseous nitrogen, enter the tube through the Ling transducer. The nitrogen gas flows through the tube section parallel to the perforated face of the test section and exits through a gap between the reflection plate and the end of the tube extension. A pitot tube is located just upstream of the test section in order to determine the velocity profile approaching the liner sample. The sound waves moving down the tube are reflected at the end plate and a standing wave is produced. The absorption characteristics of the test section are then determined as explained in Appendix B by measuring the sound pressures and phase angles with the pressure transducers.

Two cylindrical samples were tested, one with an open area ratio of 0.027 and an aperture diameter of 0.099 in.; and one with an open area ratio of 0.021 and an aperture diameter of 0.050 in. Each sample was 0.030-in. thick and had a backing cavity of 0.51 in. The tests were conducted at a constant frequency near resonance to determine the effects of flow on the acoustic resistance of each resonator configuration. The tests were originally planned to be conducted using a full 360-deg test section with a full annular backing cavity; however, severe distortion of the pressure wave was found to exist in the cavity. In order to reduce this effect, the cavity was partitioned and some of the apertures sealed off

so that acoustical data were measured only in a 45-deg test section. A tube extension, two tube diameters long, was also added to reduce the distortion effects caused by the flow being exhausted into the atmosphere.

The range of flow velocities tested was significantly restricted because of the minimum and maximum operating pressure range allowable with the Ling electropneumatic transducer. Flow-past velocities lower than 80 ft/sec could not be achieved unless gaseous nitrogen was allowed to bleed off upstream of the sample; however, this caused severe changes in the standing wave pattern produced in the tube and the resulting acoustic data could not be reproduced on successive tests. The upper velocity range was limited to approximately 300 ft/sec by the flowrate that could be obtained at the maximum transducer inlet pressure.

#### 1. Acoustical Resistance Data

The results of the tests are shown in figures V-7 and V-8, in which the ratio of the acoustic resistance with flow to that with no flow has been correlated with the average flow-past velocity and with the average Mach number.

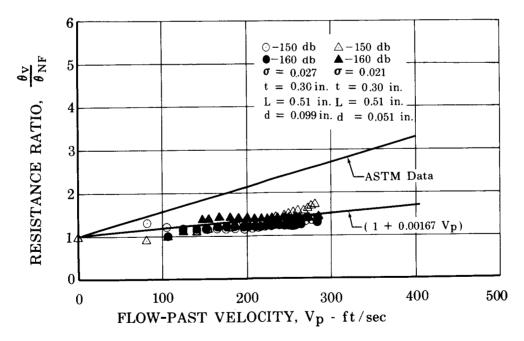


Figure V-7. Correlation of Acoustic Resistance FD 31187A
Data with Velocity of the Flow Past
the Apertures

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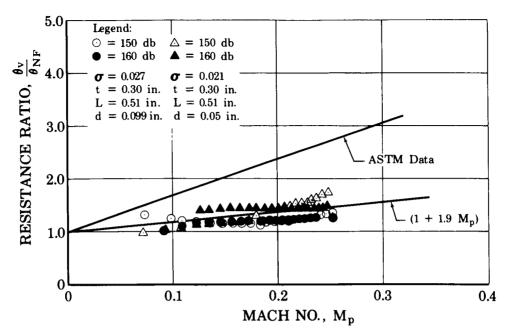


Figure V-8. Correlation of Acoustic Resistance FD 31407A

Data with Mach Number of Flow Past
the Apertures

The following empirical equations were developed relating the change in acoustic resistance with the average flow past:

$$\theta_{V} = \theta_{NF} (1 + 0.00167 V_{p})$$
 (V-8)

$$e_{V} = e_{NF} (1 + 1.9 M_{p})$$
 (V-9)

Figures V-7 and V-8 contain previous data obtained with the ASTM-type impedance apparatus for the purposes of comparison. The data clearly shows that the average flow past the sample has a much smaller effect on the resistance than has been previously determined with the ASTM impedance apparatus.

#### 2. Acoustical Reactance Data

It has been shown in the past that the acoustic reactance for no flow can be determined by the equation:

$$\chi_{\rm NF} = \frac{2\pi}{c} \frac{\ell_{\rm eff}}{\sigma} f - \frac{c}{2\pi Lf}$$
 (V-10)

The term containing  $\ell_{
m eff}$  is the inertance, and the term containing L is the capacitance. To determine a correlation of reactance to velocity

past only the inertance data need be used since the capacitance is an exact term. Furthermore, only the effective aperture length need be correlated with the flow-past, because it is the only part of the inertance that is not exact. The results of this comparison are shown in figure V-9. An empirical equation relating the effective aperture length with flow velocity was found to be as follows:

$$(\ell_{\text{eff}})_{\text{V}} = \ell_{\text{eff}_{\text{NF}}} (1 - 0.00143 \, \text{V}_{\text{p}})$$
 (V-11)

where

$$(l_{eff})_{NF} = t + d$$

If the media is other than air, equation (V-11), written in terms of the Mach number, should be used, i.e.,

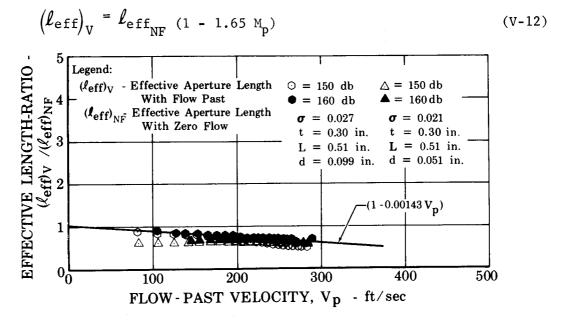


Figure V-9. Effects of Velocity Past Apertures FD 31408A on Effective Aperture Length

Figures V-10 and V-11 show a comparison of the reactance data computed using equation (V-11) substituted for  $\ell_{\rm eff}$  of equation (V-10) and the experimental reactance determined by the pressure phase data. A significant amount of data scatter was found to exist with the maximum error being 23.2%. It was concluded from the results that further experiments should be conducted with samples or various thickness, open area, and aperture to determine a more acceptable correlation.

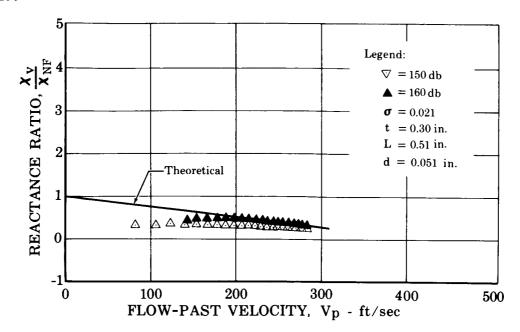


Figure V-10. Comparison of Reactance Data With Theory for Sample With 0.05-in. Diameter Apertures

FD 31410A

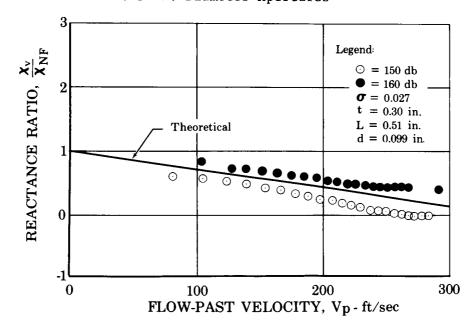
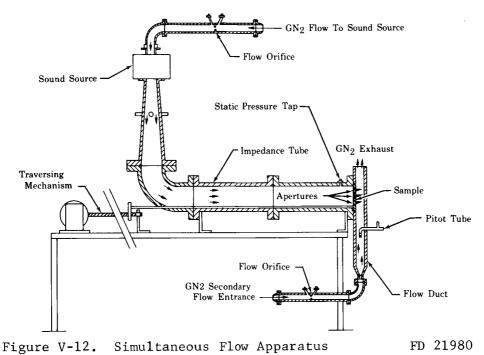


Figure V-11. Comparison of Reactance Data With Theory for Sample With 0.1-in. Diameter Apertures

FD 31409A

The exact causes of the differences between the earlier data and the pressure-phase velocity data are not presently known; however, they are believed to be due to the differences in the test procedures. The earlier data were obtained with an ASTM-type impedance apparatus in which the test sample was a flat plate and did not have a closed volume backing cavity. (See figure V-12.) This allowed the incident sound

wave to pass through the apertures of the sample and be carried out the flow-duct instead of interacting in the cavity and reradiating back into the impedance tube. Also, in the ASTM-type experiments a probe tube was used to investigate the standing wave which is established in a gaseous media flowing toward the sample. This flow toward the sample can distort the standing wave pattern along the length of the tube. Since the acoustic characteristics depend on the probe tube measuring the pressure maximum and minimum and their distances from the sample, the wave distortion can cause errors of unknown magnitude in the data.



It is recommended that further experiments should be conducted to better define the effect of higher gas velocities on the acoustic characteristic of a resonator. The experiments should be conducted with flow of different density to determine if the flow effects are dependent upon velocity or Mach No. and with samples of various thickness, open area ratio, backing cavity depth, and aperture diameter.

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# APPENDIX A APPLICATION OF THEORY

#### 1. DEVELOPMENT OF DESIGN EQUATIONS

An absorbing liner may consist of a perforated cylindrical element that is concentric to, and separated from, the combustion chamber pressure shell by support rings. In principle, the liner is composed of a parallel array of Helmholtz-type resonators that when properly designed can absorb large amounts of energy. In the following paragraphs the phenomenological correlation predicting the acoustic resistance as a function of particle velocity is used to develop equations for a new liner design technique. This technique produces the optimized liner design for a given case of instability.

The specific impedance of a Helmholtz resonator (Reference 12) is defined as:

$$Z = \frac{g}{\rho c} \frac{P_1}{u} \tag{A-1}$$

for an array of resonators equation (A-1) becomes

$$Z = \frac{g}{\rho c} \frac{P_1}{\sigma_1 u}$$
 (A-2)

where (Reference 2)

$$\sigma_1 = \frac{\sigma}{1 - \sigma^2} \tag{A-3}$$

which is a correction for high open area ratios. The specific impedance is made up of real and imaginary components in the following manner:

$$Z = (\theta + iX), \qquad (A-4)$$

Substituting equation (A-4) into equation (A-1) and solving for the particle velocity, u, gives

$$u = \frac{g}{\sigma_1 \rho_c} \frac{P_1}{(\theta + iX)}$$
 (A-5)

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Using the phenomenological correlation for the acoustic resistance (Section III)

$$R = \frac{0.37 \, \rho_{\mathrm{u}}}{C_{\mathrm{f}}^2} \tag{A-6}$$

and converting to specific acoustic resistance by use of the relationship

$$\theta = \frac{R}{\sigma_1 \rho c} \tag{A-7}$$

gives

$$\theta = \frac{0.37 \text{ u}}{\sigma_{1} \text{ cC}_{f}^{2}} \tag{A-8}$$

Substituting equation (A-5) into equation (A-8), squaring to eliminate the imaginary term, and rearranging gives

$$u^4 + (2.7\sigma_1 cC_f^2 ux)^2 = \left(\frac{P_1C_f^2g}{0.37\rho}\right)^2$$
 (A-9)

At resonance the reactance (X) is zero, therefore, equation (A-9) reduces to

$$u_o = \sqrt{\frac{P_1 C_f^2 g}{0.37 \rho}}$$
 (A-10)

It is important to note that the particle velocity at resonance is independent of the liner configuration and depends only on the total pressure; experimental results from the present program are in excellent agreement with equation (A-10). (See figure A-1.)

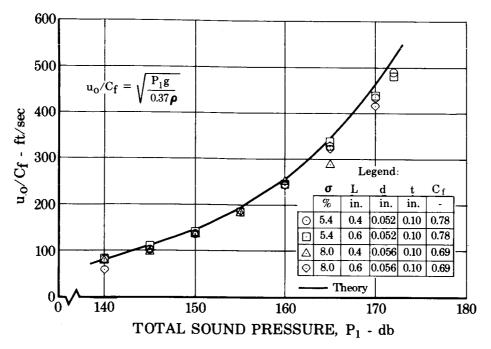


Figure A-1. Correlation of the Orifice Particle FD 31186
Velocity at Resonance with the Total
Sound Pressure

#### 2. ABSORBING LINER CALCULATIONS

The following calculations illustrate a method that gives the optimized liner design for an assumed level of absorption desired at the frequency of instability. The gas properties and flow coefficient assumed for this example are

$$\rho = 0.075 \text{ lb}_{\text{m}}/\text{ft}^{3}$$
 $c = 1130 \text{ ft/sec}$ 
 $c_{\text{f}} = 0.78$ 

It is assumed that the flow coefficient can be controlled when the liner is fabricated. The peak combustion pressure oscillation amplitude is assumed to be 159  ${\rm db}^{*}$  (Reference 0.0002 microbar) occurring at a frequency of 2000 Hz.

\*A low sound pressure was assumed so that the resulting configuration could be tested with the high frequency impedance measuring apparatus. In normal application to rocket chambers this value would correspond to a sound level of 180 to 190 decibels.

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A. No Flow or Flow Past Calculations

#### 1. Conditions at Resonance

The resonant frequency of the liner design is taken to be the frequency at which the highest level of instability is expected to occur. Assume the amount of absorption that is required at resonance to stabilize combustion is 90%. It is believed that 50% absorption in a rocket chamber is sufficient to suppress most instabilities to an acceptable level. If higher absorption values (above 80%) are desired at sound levels greater than 170 db, large open area ratios (25% or greater) are necessary which are impractical for applications to rocket engines. If, however, the liner is to be used under conditions where high open area ratios are acceptable, then high absorption values can be assumed.

The absorption coefficient is defined as

$$\alpha = \frac{4\theta}{(\theta + 1)^2 + \chi^2} . \tag{A-11}$$

For 90% absorption at resonance (x = 0) the required resistance can be solved for

$$0.90 = \frac{4\theta_0}{(\theta_0 + 1)^2}$$

$$\theta_0^2 - 2.44 \theta_0 + 1 = 0$$

$$\theta_0 = 1.92; \ 0.02^*$$

With a steady flow  $(M_p)$  of gas past the liner it is necessary to determine the resistance of the liner if no flow were present by using the relationship developed in Section V, which describes the effects of flow past on the resistance.

$$\theta_{\rm NF} = \theta_{\rm Mp} / (1 + 1.9 \,{\rm Mp})$$
 (A-12)

<sup>\*</sup>According to Reference (13), only values of  $\theta \ge 1$  should be used in this type of design analysis; therefore, the lower value of  $\theta_0$  should be ignored.

where  $\theta_{\rm MP}$  is  $\theta_{\rm O}$ , the resistance required for 90% absorption at resonance. In the example calculations Mp = 0 then

$$\theta_{\rm NF} = \theta_{\rm MP} = 1.92$$

The particle velocity at resonance is given by equation (A-10)

$$u_o = \sqrt{\frac{P_1 c_f^2 g}{0.37 \rho}}$$

where  $P_1$  is 159 db (Reference 0.0002 microbar) or  $53-lb_f/ft^2$ 

$$u_o = \sqrt{\frac{(53)(0.78)^2(32.2)}{(0.37)(0.075)}}$$

$$u_0 = 191 \text{ ft/sec}$$

Now the resistance and particle velocity at resonance are known and the required open area ratio satisfying these values are obtained from equation (A-8)

$$\theta_{\rm NF} = \frac{0.37 \text{ u}_{\rm o}}{{\rm C_f}^2 \sigma_{\rm 1} {\rm c}}$$

$$\sigma_{1} = \frac{0.37 \text{ u}_{0}}{c_{f}^{2} c \theta_{NF}}$$

$$= \frac{(0.37) (191)}{(0.78)^{2} (1130) (1.92)}$$

$$= 0.054$$

using equation (A-3) gives

$$0.054 = \frac{\sigma}{1 - \sigma^2}$$

$$\sigma^2 + 18.5 \sigma - 1 = 0$$

$$\sigma = 0.054$$

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At this point it is necessary to assume a liner aperture diameter and liner thickness:

d = 0.052 in.

t = 0.10 in.

Using the expression for the effective length (see Section V) with flow past the liner gives

$$\ell_{\text{eff}} = \left(\frac{t}{12} + \frac{d}{12}\right) \left(1 - 1.6 \text{ M}_{\text{p}}\right)$$

$$= 0.013 \text{ ft where for this case M}_{\text{p}} = 0.$$
(A-13)

Now the required backing distance of the liner cavity is calculated from the equation for resonant frequency.

$$f_{o} = \frac{c}{2\pi} \sqrt{\frac{\sigma_{1}}{L \, \ell_{eff}}}$$

$$L = \left(\frac{c}{2\pi \, f_{o}}\right)^{2} \frac{\sigma_{1}}{\ell_{eff}}$$

$$L = \left(\frac{1130}{2(3.14)(2000)}\right)^{2} \left(\frac{0.054}{0.013}\right)$$

L = 0.035 ft

L = 0.415 in.

This sets all liner parameters to give 90% absorption at 2000 Hz, with no flow past the liner. A summary of the liner design shows

 $\sigma = 5.4\%$ 

L = 0.415 in.

d = 0.052 in.

t = 0.10 in.

 $u_0 = 191 \text{ ft/sec}$ 

#### 2. Nonresonant Conditions

It is necessary to investigate if this liner has sufficient absorption at frequencies other than that of resonance. The maximum particle velocity occurs at resonance, therefore, a particle velocity which is

less than the value calculated at resonance can be chosen and used in equation (A-9) to compute the reactance. This technique applies only for particle velocities that are in the nonlinear range; i.e.,  $\geq$  60 ft/sec.

To determine the reactance, use equation (A-9) and substitute the results of equation (A-10), giving

$$u^{4} + \left(\frac{\sigma_{1}^{C_{1}^{2}cu}x}{0.37}\right)^{2} = u_{0}^{4} \tag{A-15}$$

Assume a particle velocity less than that at resonance

$$u = 180 \text{ ft/sec}$$

Solving equation (A-15) for the specific reactance ( $\chi$ ) gives

$$(180)^{4} + \left(\frac{0.054 (0.78)^{2} (1130) (180)}{0.37}\right)^{2} x^{2} = (191)^{4}$$

$$x = \pm 0.92$$

where the negative reactance corresponds to a frequency below resonance and the positive value to a frequency above resonance. Using a definition for specific reactance (Reference 2) the frequencies for the above values are calculated

$$x = \frac{2\pi}{c} \frac{\ell_{eff}}{\sigma_{1}} \quad f - \frac{c}{2\pi} \frac{1}{L} \frac{1}{f}$$

$$\pm 0.92 = \frac{2 (3.14)}{1130} \left(\frac{0.013}{0.054}\right) \quad f - \left(\frac{1130}{2(3.14) (0.035)}\right) \quad \frac{1}{f}$$
(A-16)

$$f = 1651 \text{ for } X = -0.92$$

$$f = 2409 \text{ for } X = +0.92$$

Now the resistance with a particle velocity of 180 ft/sec is determined from equation (A-8)

$$\theta = \frac{0.37 \text{ u}}{\sigma_1 \text{ cC}_f^2}$$

$$= \frac{0.37(180)}{(0.054)(1130)(0.78)^2}$$

$$\theta = 1.8$$

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The resistance is now corrected to account for the effects of flow past the liner

$$\theta_{M_{p}} = \theta (1 + 1.9 M_{p})$$

$$\theta_{M_{p}} = \theta = 1.8 \text{ since } M_{p} = 0$$
(A-17)

The absorption coefficient at both frequencies is determined from equation (A-11)

$$\alpha = \frac{4\theta}{(\theta + 1)^2 + \chi^2}$$

$$= \frac{4(1.8)}{(1.8 + 1)^2 + (0.92)^2}$$

$$= 0.83$$

$$\alpha = 83\%$$

The absorption coefficient at frequencies farther from resonance is determined by assuming increasingly smaller particle velocities below the maximum value at resonance and repeating the process which follows equation A-15.

The liner designed for the no flow case ( $M_p = 0$ ) was tested with the high frequency impedance apparatus so that a comparison of the design results with the actual experimental results could be made. Figure A-2 shows the absorption coefficient versus frequency for the experimental results compared with the new design theory and old theory which calculated the resistance by use of the nonlinear correction term. A comparison of the individual acoustic components are shown in table A-1 where the subscript E refers to the experimental results.

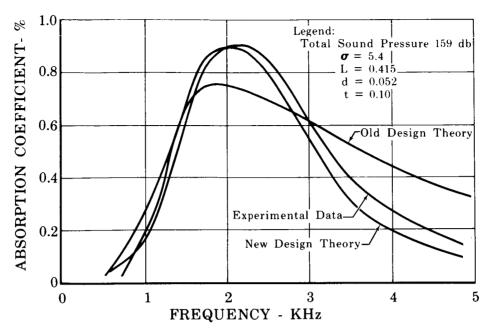


Figure A-2. Comparison of Experimental Results FD 31185 With the New and Old Design Theories

Table A-1. Comparison of Design Theory With Experimental Results

f, Hz	u, ft/sec	ue, ft/sec	θ	$m{ heta}_{ m E}$	x	$x_{\rm E}$	lpha , %	α <sub>Ε</sub> , %
645	50	46	0.5	0.9	<b>-7.3</b>	-8.0	4	5
835	70	62	0.7	1.0	<b>-</b> 5.2	<b>-</b> 5.8	10	10
995	90	80	0.9	1.0	-4.0	-4.4	19	16
1135	110	99	1.1	1.2	-3.1	-3.4	29	29
1260	130	115	1.3	1.3	<b>-2.</b> 5	<b>-2.</b> 9	46	38
1401	150	135	1.5	1.6	<b>-1.9</b>	-2.1	61	56
1561	170	151	1.7	1.7	-1.3	-1.6	76	68
1651	180	160	1.8	1.8	-0.9	-1.3	83	76
2000	191	179	1.9	1.9	0.0	-0.1	90	90
2409	180	173	1.8	1.8	0.9	0.7	83	86
2561	170	173	1.6	1.7	1.3	1.0	76	82
2856	150	150	1.5	1.4	1.9	1.6	61	67
3165	130	130	1.3	1.1	2.5	2.0	46	53
3525	110	113	1.1	0.9	3.1	2.4	29	37
4795	70	68	0.7	0.5	5.2	3.2	10	16

#### B. FLOW-THROUGH CALCULATIONS

For an example calculation assume a Mach number of net flow through the apertures

$$M_{T} = 0.10$$

and use the same design requirements as used for the flow-past calculations.

#### 1. Conditions at Resonance

In the flow-past calculations the particle velocity at resonance was calculated to be

$$u_0 = 191 \text{ ft/sec}$$

For air the particle velocity Mach number is

$$M_{0} = 0.17$$

Before making additional calculations it is necessary that the following condition (see Section V) be satisfied

$$M_{T} > 0.5M_{O} \tag{A-18}$$

if this condition is not met then the design calculations should be made in the same manner as for the no-flow case. Using equation (A-18), it is seen that for the sample calculation the above requirement is satisfied

$$0.1 > 0.5(0.17) = 0.085$$

The resistance at resonance was found as

$$\theta_{o} = 1.92.$$

Now the resistance at resonance and the flow through Mach number are known and the required open area ratio satisfying these values can be determined from equation (V-7).

$$\theta_{0} = \frac{M_{T}}{\sigma_{0}^{C_{f}^{3}}}$$

$$\sigma_{1} = \frac{M_{T}}{\theta_{0}^{C_{f}^{3}}}$$

$$= \frac{0.1}{1.92(0.78)3}$$

$$= 0.11$$
(A-19)

Using equation (A-3) gives

$$\sigma = 0.109$$
.

At this point it is necessary to assign a liner aperture diameter and liner thickness

$$d = 0.052 \text{ in.}$$
  
 $t = 0.10 \text{ in.}$ 

The effective length is determined as

$$\ell_{\text{eff}} = \frac{t}{12} + \frac{d}{12}$$
$$= 0.013 \text{ ft}$$

Now the required backing distance of the liner cavity is calculated as in equation (A-14)

$$L = 0.68 \text{ ft.}$$
  
 $L = 0.82 \text{ in.}$ 

This sets all liner parameters to give 90% absorption at 2000 Hz with flow through Mach number of 0.1. A summary of the liner design shows

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#### 2. Nonresonant Conditions

When condition A-18 is satisfied the resistance is determined by equation (A-19) and since the flow through is assumed to be constant then the resistance is constant over all frequencies (see Section V).

$$\theta = 1.92$$
.

The reactance is calculated from equation (A-16) by assuming a frequency

f = 1700 Hz

then

X = -0.32

The absorption coefficient is calculated from equation (A-11) and

$$\alpha = \frac{4\theta}{(\theta + 1)^2 + \chi^2}$$

$$=\frac{4(1.92)}{(1.92+1)^2+(0.32)^2}$$

 $\alpha = 0.83$ 

 $\alpha = 83\%$ 

Since the resistance is constant it is seen from equation (A-11) that the absorption coefficient is only effected by changes in reactance. To determine the absorption coefficient over a band of frequencies it is necessary to choose the frequencies, calculate the corresponding reactance and use equation (A-11) to determine the respective absorption coefficients.

# APPENDIX B PRESSURE-PHASE IMPEDANCE MEASURING TECHNIQUE

This appendix is divided into four sections; in the first a description of the basic impedance measuring apparatus is given and the necessary impedance relations are derived in the second. The error analysis of the experiment appears in the third part, and a description of the ancillary components follows.

#### 1. BASIC APPARATUS

The pressure-phase impedance device is shown in figure 3-1. The device consists of a square duct of fixed length and uniform cross section, which unlike the ASTM impedance tube, can be made as short as desired without imposing a frequency limit on the apparatus. At one end of the duct, a source of sound waves is placed, and at the other end, the specimen to be tested. An audio oscillator (signal generator) drives the speakers causing plane waves to be transmitted longitudinally along the tube.

When the longitudinal wave is incident on the sample at the end of the tube part of its energy is reflected back up the tube in the form of another pressure wave. The incident and reflected waves set up a standing wave in the tube that has a maximum pressure amplitude at the sample face, a small microphone mounted flush in the side wall of the tube at the sample is used to measure the pressure.

The portion of the incident sound energy that is not reflected back up the tube is transmitted through the apertures and into the resonator cavity. The energy in the cavity, also in the form of sound pressure, is measured with a second microphone located on the back wall of the cavity. (See figure B-2.) The outputs of both microphones are fed through a wave analyzer to a millivolt meter so that the pressure amplitudes of the sound level in front of the sample and in the cavity can be read. In addition, as shown in the schematic of figure A-3, the outputs of both microphones are connected to a synchronous filter and phase meter to determine the phase difference between the incident and transmitted waves.

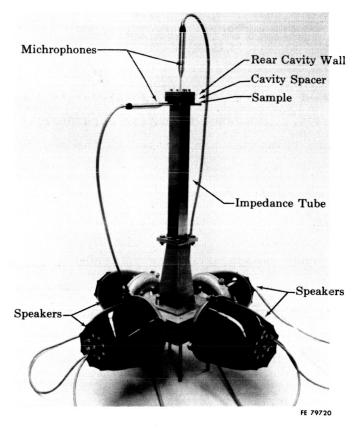


Figure B-1. High Frequency and High-Sound Pressure-Phase Angle Impedance Tube

FD 25289

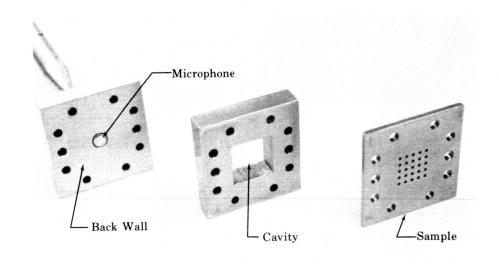


Figure B-2. Resonator Test Section

FD 23078

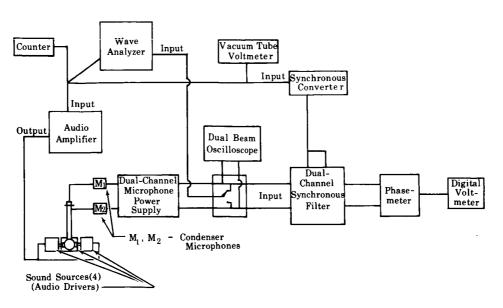


Figure B-3. Schematic of Pressure Phase Impedance Measuring Apparatus

FD 29167

#### 2. DERIVIATION OF IMPEDANCE RELATIONS

A typical Helmholtz resonator at the end of a tube is shown in figure B-4. Also shown are two microphones, one mounted in the side wall to measure the sound pressure in front of the sample,  $P_1$ , and one on the rear wall to measure the sound pressure in the cavity,  $P_2$ . With the signals from both microphones the phase difference,  $\phi$ , between the two pressures can be determined.

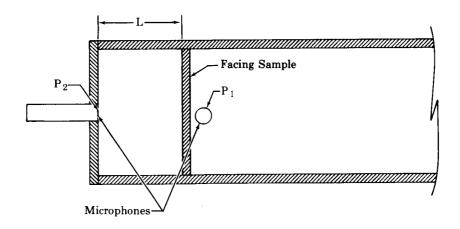


Figure B-4. Helmholtz Resonator in Impedance
Tube

FD 23080

The total impedance of a resonator assembly is composed of two parts

$$Z_{\text{total}} = Z_{\text{plate}} + Z_{\text{air cavity}}$$
 (B-1)

If u is the oscillatory gas velocity amplitude in the apertures and  $\rho$  and c are the density and sonic velocity, respectively of the test media,  $\sigma$  is the ratio of the area of the apertures to the cross-sectional area of the tube, by definition the impedance is the complex ratio of the pressure difference and the particle velocity

$$z_{\text{plate}} = \frac{\overline{P}_1 - \overline{P}_2}{\sigma \rho cu}$$
 (B-2)

and also for a partitioned cavity

$$Z_{\text{air cavity}} = \frac{P_2}{\sigma_{\text{cu}}\rho} = \frac{i}{kL}$$
 (B-3)

Solving equation (B-2) for u, substituting into equation (B-3) and solving for  $Z_{\text{plate}}$  gives:

$$Z_{\text{plate}} = \frac{i}{kL} \left[ \frac{P_1}{P_2} - 1 \right]$$
 (B-4)

where k, the wave number, is defined as  $k = \omega/c$ .

Using a mathematical identity, the ratio of the complex pressures can be expressed as:

$$\frac{P_1}{P_2} = \left[\frac{P_1}{P_2}\right] e^{-i\phi} = \left[\frac{P_1}{P_2}\right] \cos \phi - i \left[\frac{P_1}{P_2}\right] \sin \phi$$

Substituting the identity into equation (B-4)

$$Z_{\text{plate}} = \frac{1}{kL} \left[ \frac{P_1}{P_2} \right] \sin \phi - \frac{i}{kL} \left[ 1 - \frac{P_1}{P_2} \cos \phi \right]$$

Solving equation (B-1) for  $Z_{total}$  gives:

$$Z_{\text{total}} = \frac{1}{kL} \left[ \frac{P_1}{P_2} \right] \sin \phi - \frac{i}{kL} \left[ 1 - \left| \frac{P_1}{P_2} \right| \cos \phi \right] + \frac{i}{kL}$$
 (B-5)

or

$$Z_{\text{total}} = \frac{1}{kL} \left[ \frac{P_1}{P_2} \right] \sin \phi + i \left[ \frac{1}{kL} \left| \frac{P_1}{P_2} \right| \cos \phi \right]$$
 (B-6)

The total impedance is a complex sum; the real part is the resistance,  $\theta$ , and the imaginary part is the reactance,  $\chi$ . By inspection of equation (A-6) it is evident that the resistance can be determined from

$$\theta = \frac{1}{kL} \left[ \frac{P_1}{P_2} \right] \sin \phi \tag{B-7}$$

and the reactance from

$$X = -\frac{1}{kL} \left[ \frac{P_1}{P_2} \right] \cos \phi \tag{B-8}$$

As shown in Reference 5, the normal incident sound pressure can be obtained from

$$P_{i} = P_{1} / \left[ 1 + \frac{Z-1}{Z+1} \right] = P_{1} / \left[ 1 + \left( \frac{(\theta - 1)^{2} + \chi^{2}}{(\theta + 1)^{2} + \chi^{2}} \right)^{\frac{1}{2}} \right]$$
 (B-9)

Additional acoustic parameters that can now be computed are:

Absorption coefficient

$$\alpha = \frac{4\theta}{(\theta + 1)^2 + \chi^2} \tag{B-10}$$

Nonlinear resistance correction factor

$$\Delta_{\rm n} \ell / d = \frac{\theta \sigma_{\rm c}}{\sqrt{8\nu\omega}} - (t/d + 1)$$
 (B-11)

where

 $\sigma$  is the open area ratio of the facing,

 $\boldsymbol{\nu}$  is the kinematic viscosity of the media and

 $\omega$  is the angular frequency

In addition, the oscillatory flow velocity in apertures is computed using equation (B-3)

$$u = kLP_2/(\sigma \rho c)$$
 (B-12)

and the aperture effective length is obtained by setting the inertance of the sample (Reference 5) equal to the impedance of the plate (equation B-4)

$$\ell_{eff} = \frac{\sigma_{cZ_{plate}}}{2\pi f} = \frac{\sigma_{c}}{2\pi f kL} \left[ \frac{P_{1}}{P_{2}} - 1 \right]$$
 (B-13)

#### 3. ERROR ANALYSIS OF TECHNIQUE

An error analysis of the pressure-phase angle method of determining the acoustical properties of a liner was performed using the "method of partial derivatives." (See Reference 9.) According to this method, the error in a calculated value may be approximated as

$$\sigma_{F}^{2} = \left(\frac{\partial F}{\partial X_{1}}\right)^{2} \sigma_{X_{1}}^{2} + \left(\frac{\partial F}{\partial X_{2}}\right)^{2} \sigma_{X_{2}}^{2} + \dots + \left(\frac{\partial F}{\partial X_{n}}\right)^{2} \sigma_{X_{n}}^{2}$$
(B-14)

where F is the calculated function

 $\mathbf{X}_1$ ,  $\mathbf{X}_2$ , ...  $\mathbf{X}_n$  are the variables used in calculating the function

 $\frac{\partial F}{\partial x_1}$ ,  $\frac{\partial F}{\partial x_2}$ , ...  $\frac{\partial F}{\partial x_n}$  are the partial derivatives of the calculated function with respect to the variables  $x_1$ ,  $x_2$ , ...  $x_n$ 

 $\sigma_{X_1}$ ,  $\sigma_{X_2}$ , ...  $\sigma_{X_n}$  are the estimated errors in measurement of the variables  $x_1$ ,  $x_2$ , ...  $x_n$ 

and  $\sigma_F$  is the estimated error in the calculated function due to the errors in the measurement of the variables  $X_1$ ,  $X_2$ , ...  $X_n$ .

In using the pressure-phase angle method for determining the acoustical properties of a liner the following variables must be measured:

- 1. Sound pressure level in front of the liner
- 2. Sound pressure level in the cavity
- 3. Frequency of the sound pressure oscillations
- 4. Phase angle between these sound pressures
- 5. Gas properties of the system
- 6. Geometry of the system.

For this analysis, it was assumed that there was no error in measuring the geometry of the system and that the gas properties contributed no error. Thus, only the two sound pressure levels and the phase angle between them were considered in estimating errors.

It is believed that these are valid assumptions for impedance tube testing or other experiments where the geometry and gas properties are well known. For hot testing, an analysis should be carried out which considers all of the variables because gas properties and even parts of the geometry may not be well known.

The following calculated values were analyzed:

- 1. Gas particle velocity in the aperture, u
- 2. Resistance, R
- 3. Reactance, X
- 4. Impedance, Z
- 5. Absorption coefficient,  $\alpha$
- 6. Incident Pressure, P<sub>i</sub>.

Each of these parameters were analyzed in the same fashion. An equation for the parameter was written in terms of the variables listed above, and then the appropriate partial derivatives were taken and inserted in the general equation (B-14). The results are given below.

a. Gas Particle Velocity in the Aperture, u

$$\boldsymbol{\sigma}_{\mathbf{u}} = (0.115 \, \boldsymbol{\sigma}_{\mathbf{db}_2}) \, \mathbf{u} \tag{B-15}$$

and  $\sigma_{
m db}_2$  is the estimated error in measurement of cavity SPL in db.

Thus, an error of 11.5% per db of error in measuring cavity SPL is estimated. If an error of 0.5 db is estimated in cavity SPL measurement, then the estimated error in u is 5.75%.

#### b. Resistance, R

$$\sigma_{R} = \sqrt{\sigma^{2}_{(R/\text{phase})} + \sigma^{2}_{(R/\text{SPL})}}$$
 (B-16)

where

 ${\pmb \sigma}_{\rm R}$  is the estimated error in R

 $\sigma_{(\text{R/phase})}$  is the estimated error in R due to error in phase angle measurement

 $\sigma_{(\text{R/SPL})}$  is the estimated error in R due to error in SPL measurement;

and

$$\boldsymbol{\sigma}_{(R/SPL)} = \left(0.115 \sqrt{\boldsymbol{\sigma}_{db_1}^2 + \boldsymbol{\sigma}_{db_2}^2}\right) R$$
 (B-17)

$$\boldsymbol{\sigma}_{(R/\text{phase})} = \left[0.0174 \ (\cot \boldsymbol{\phi}) \boldsymbol{\sigma} \boldsymbol{\phi}\right] R \tag{B-18}$$

where

 $\phi$  is the phase angle

 $\sigma\phi$  is the estimated error in phase angle measurement

 $\pmb{\sigma}_{\text{db}\,1}$  is the estimated error in measurement of SPL in front of the liner

 $\sigma_{db_2}$  is the estimated error in measurement of cavity SPL.

The  $\sigma_{(R/phase)}$  is negligible except below 10 deg and above 170 deg. (See figure B-5.) Between 10 deg and 170 deg,  $\sigma_R$  is approximately equal to  $\sigma_{(R/SPL)}$ , which for  $\sigma_{db_1} = \sigma_{db_2} = 0.5$  yields an estimated error of 8.1% in R.

c. Reactance, X

$$\sigma_{X} = \sqrt{\sigma_{(X/SPL)}^{2} + \sigma_{(X/Phase)}^{2}}$$
 (B-19)

where the terminology is the same as above for resistance

and

$$\sigma_{(X/SPL)} = \left(0.115\sqrt{\sigma_{db_1}^2 + \sigma_{db_2}^2}\right) X$$
 (B-20)

$$\sigma_{(X/\text{phase})} = \left[0.0174 \ (\tan \phi) \sigma \phi\right] X.$$
 (B-21)

The error indicated here is similar to that given above for resistance, except that the region of high error here is between 80 deg and 100 deg because of the tan  $\phi$  term. (See figure B-6).

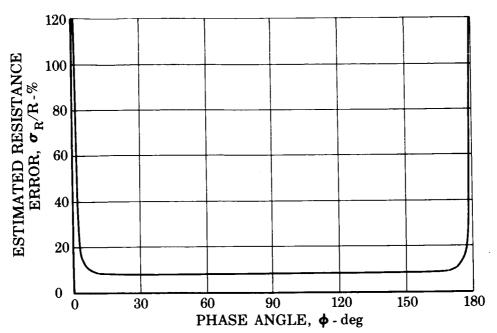


Figure B-5. Estimated Resistance Error as a Function of Phase Angle

FD 29169

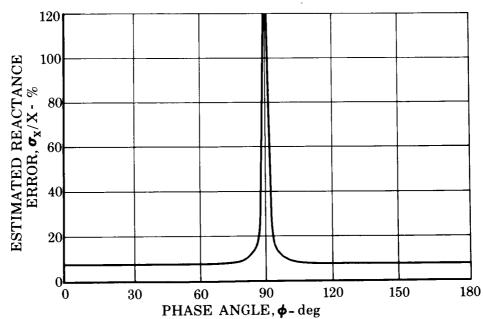


Figure B-6. Estimated Reactance Error as a Function of Phase Angle

FD 29170

d. Impedance, Z

$$\sigma_{Z} = \left(0.115 \sqrt{\sigma_{db_{1}}^{2} + \sigma_{db_{2}}^{2}}\right) Z$$
(B-22)

where  $\sigma_{\rm Z}$  (the estimated error in calculating Z (is 11.5% per unit value of the radical. For  $\sigma_{\rm db_1}$  =  $\sigma_{\rm db_2}$  = 0.5, we get an estimated error of 8.1%.

e. Absorption Coefficient,  $\alpha$ 

$$\sigma_{\alpha} = \left[0.115 \left(\frac{Z-1}{Z+1}\right) \sqrt{\sigma_{db_1}^2 + \sigma_{db_2}^2}\right] \alpha$$
 (B-23)

since Z is positive,  $\sigma_{\alpha}$  (the estimated error in  $\alpha$ ) should always be less than or equal to 11.5% per unit value of the radical. For  $\sigma_{\rm db_1}$  =  $\sigma_{\rm db_2}$  = 0.5, the estimated error always is less than or equal to 8.1%.

f. Incident Pressure, P

$$\sigma_{P_{i}} = \sqrt{\sigma_{(P_{i}/db_{1})}^{2} + \sigma_{(P_{i}/Z)}^{2}}$$
 (B-24)

where

 $oldsymbol{\sigma}_{ exttt{P}_{f i}}$  is the estimated error in  $exttt{P}_{f i}$ 

 ${\pmb \sigma}_{(P_1/db_1)}$  is the estimated error in P because of errors in measuring sound pressure level in front of the liner

 $\sigma_{(P_i/Z)}$  is the estimated error in P due to errors in calculating Z

and

$$\sigma_{(P_1/db_1)} = 0.115 \sigma_{db_1} P_1$$
 (B-25)

$$\sigma_{(P_i/Z)} = \frac{\sigma_Z}{Z(Z+1)} P_i$$
 (B-26)

Combining these equations we have

$$\sigma_{P_{i}} = 0.115 P_{i} \sqrt{\sigma_{db_{1}}^{2} + \frac{\sigma_{db_{1}}^{2} + \sigma_{db_{2}}^{2}}{\left[z (z + 1)\right]^{2}}}$$

Using  $\sigma_{\mathrm{db}_1} = \sigma_{\mathrm{db}_2} = 0.5$ , we have

$$\sigma_{P_{i}} = \left(0.115\sqrt{0.25 + \frac{0.5}{[z (z + 1)]^{2}}}\right)P_{i}$$
 (B-27)

The second term under the radical is negligible when Z > 1. So the estimated error in  $P_i$  is approximately 5.75% for Z > 1. For 0.5 < Z < 1, the estimated error is less than 12.5%. For  $Z \le 0.5$  the error increases rapidly. (See figure B-7.)

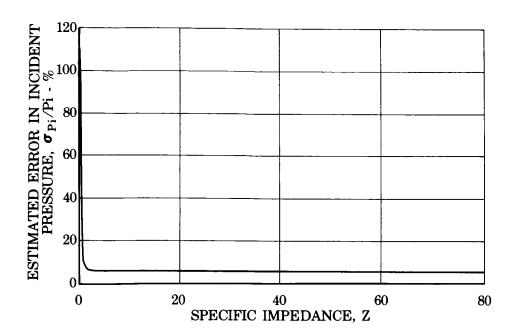


Figure B-7. Estimated Error in Incident Sound Pressure as a Function of Impedance

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#### g. Conclusions

It can be concluded from this analysis that in impedance tube testing or other cold flow experiments in which the gas properties and geometry are well known, error in acquisition of data should not prevent good calculated results if care is taken to assure that no large errors are incurred in sound pressure or phase angle measurement. Exceptions are given below. Large estimated errors occur when calculating

- 1. Resistance at phase angles of less than 10 deg or more than 170 deg
- 2. Reactance at phase angles between 80 deg and 100 deg
- 3. Incident pressure when the calculated impedance is less than 0.5.

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#### 4. ANCILLARY COMPONENTS

The ancillary components used with the apparatus are:

Component Manufacturing and Model Number Wave Analyzer General Radio - Model 1900-A Audio Amplifier Harman Kardon - Model BA-150 Watt Hewlett Packard - Model 521CR Electronic Counter Condenser Microphones M<sub>1</sub> & M<sub>2</sub> - Bruel & Kjaer - Model 4138, plus UA 0036 adapter, also 2615 cathode follower Bruel & Kjaer - Model 2803 Dual-Channel Power Supplies Manufacturing and Model Number Component Hewlett Packard - Model 132A Dual-Beam Oscilloscope Hewlett Packard - Model 400DR Vacuum Tube Voltmeter Dual-Channel Synchronous Filter AD-YU Electronics - Model 1034 AD-YU Electronics - Model 1036 Synchronous Converter AD-YU Electronics - Model 524A3 Digital Phase Computer Honeywell - Model DC-110BR, or Precisions DC Voltmeter optional Digital Voltmeter. Bruel & Kjaer - Model 4220 (for Pistonphone microphone calibrations) Atlas Sound Driver Unit - Model PD-60T Sound Sources

The function of each component is as follows:

- 1. The GR1900-A Wave Analyzer measures the output of the microphones through an adjustable narrow (± 3, 10 or 50 Hz) band-pass filter. The analyzer's tracking generator output provides the driving signal.
- 2. The Counter and Vacuum Tube Voltmeter are used to monitor the frequency and amplitude of the driving signal.
- 3. The Audio Amplifier boosts the power of the driving signal to the level required.
- 4. The Audio Driver converts the electrical signal to sound.
- 5. The Condenser Microphones provide electrical signals equivalent to sound pressure level.
- 6. The Microphone Power Supply provides the polarization voltage to the microphones and contains an attenuator for standardization and an emitter follower for isolation.
- 7. The Dual Beam Scope is used to monitor microphone outputs for approximate level and phase and for distortion.

8. The block diagram of the Type 1034 Dual-Channel Syncronous Filter is shown in figure B-8. Since both channels are identical, only channel 1 is shown and described.

The distorted, and/or noisy signal is amplified before being applied to the balanced mixer circuitry through an emitter-follower. The balanced mixer also receives signals from an emitter-follower, the frequency of which is the syncronized input (a 2.4 volt signal containing the carrier frequency mixed with an audio frequency which is the fundamental frequency of the distorted signal input. Both input circuits contain emitter-followers in order to provide high input impedances. The output of the balanced mixes is fed to the crystal filter, from which only the recovered carrier frequency (with amplitude proportional to the fundamental component of the distorted signal input, and with phase angle equal to that input) is allowed to emerge. After two stages of amplification an LC filter circuit is used to provide even greater purity of the recovered carrier. One stage of the output amplifier provides voltage amplification, while the other stage provides three low impedance outputs; both "HI" and "LO" outputs and a selectable D.C. metering circuit.

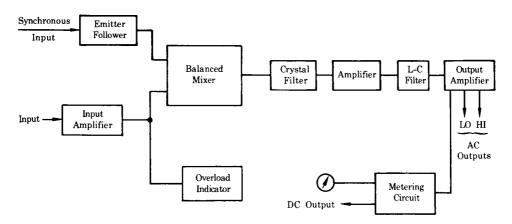


Figure B-8. Block Diagram of One Channel of FD 29168
Model 1034 Dual-Channel Synchronous Filter

9. Type 1036 Synchronous Converter is especially designed to be used together with Type 1034 Dual-Channel Synchronous Filter. Figure B-9 shows a block diagram of Type 1036. (Ea is a synchronized audio signal. The output signal has constant amplitude and frequency equal to crystal frequency plus input signal frequency.) The input amplifier provides a high input impedance. The wideband 90-deg phase shifter produces two signals,  $E_a$  and  $E_a$  + 90°. These two signals have exactly 90-deg phase difference and equal amplitude. The frequency equals that of the input audio signal,  $f_a$ , and changes as the frequency of the input signal changes. The two balanced mixers produce  $E_1$  and  $E_2$ , containing only

the upper and lower sidebands of their inputs (suppressed carrier). The crystal oscillator supplies signal,  $E_c$ , at the exact center frequency of the crystal filters used in Type 1034 Dual-Channel Synchronous Filter. The 90-deg phase shifter generates two outputs,  $E_c$  and  $E_c+90^{\circ}$ , with equal amplitude. Since the amplitudes of  $E_a$  and  $E_a+90$ -deg are equal and their frequencies always follow the input audio frequency,  $W_a$ , one can write two expressions for the output of the balanced mixers,  $E_1$  and  $E_2$ , as follows:

$$E_1 = kE_aE_c \sin (W_c + W_a)t - \sin (W_c - W_a) t$$

$$E_2 = kE_aE_c \sin (W_c + W_a)t + \sin (W_c - W_a) t$$

The sum amplifier accepts  $E_1$  and  $E_2$  and produces its algebraic sum,  $E_3$ , such as  $E_3 = E_1 + E_2 = 2kE_aE_c$  sin  $(W_c + W_a)$  t. The output amplifier provides low output impedance to drive up to 40 channels of Type 1034 Synchronous Filter. The voltmeter circuit can be switched by panel control to read the amplitude of either the output signal or input signal on the panel meter.

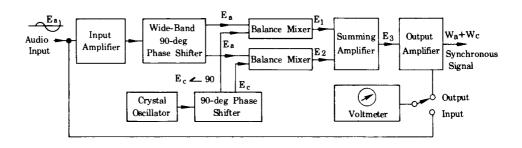


Figure B-9. Block Diagram of Type 1036 Syn- FD 29163 chronous Connecter

- 10. The Type 524A Phase Meter provides a D.C. level output proportional to the phase difference between it's inputs.
- 11. The Digital Voltmeter measures the phase meter output and by means of an AC to DC converter can read the synchronous filter's outputs as an additional measure of sound pressure level.

# APPENDIX C FLOW COEFFICIENT EXPERIMENTS

In order to explain the high frequency test results, an experiment was performed to determine if the hydraulic flow coefficient of the sample orifices was related to the sample-to-sample differences in the acoustic resistance and particle velocity data. The flow coefficient  $(C_{\rm f})$  of each sample was calculated from the following equation (Reference 11).

$$w = C_f A_2 Y_1 \sqrt{\frac{2g\rho_1 \Delta p}{1 - \beta^4}}$$
 (C-1)

where

w = mass flowrate

 $A_2$  = orifice flow area

 $Y_1$  = expansion factor accounting for effects of compressive flow

g = gravitational constant

 $\rho_1$  = upstream fluid density

 $\Delta p$  = pressure differential across the orifice

 $\beta$  = ratio of upstream to orifice diameters.

A flow rig (figure C-1) was fabricated for the experiment. The rig consisted of a plenum chamber supplied with a metered quantity of nitrogen which was allowed to vent through the sample apertures. A static pressure tap was located upstream of the sample. A spacer plate which formed the cavity side walls in the high frequency tests was installed downstream of the sample to simulate any wall effects on the flow exhausting from the apertures.

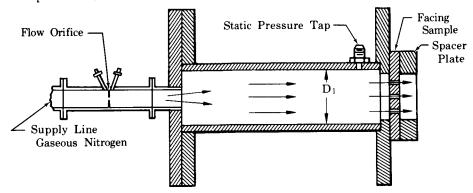


Figure C-1. Apparatus for Measuring Resonator Facing Flow Coefficient

FD 29164

The following procedure was used in evaluating the flow coefficient by use of equation C-1. The mass flowrate was determined by use of a calibrated flowmeter. The orifice flow area,  $A_2$ , was taken to be that of a single orifice having the same area as the total area of all the small apertures in the sample. The expansion factor was calculated from the following equation (Reference 11).

$$Y_{1} = \sqrt{\frac{\left[\gamma/(\gamma-1)\right] r^{2/\gamma} \left[1 - r^{(\gamma-1)/\gamma}\right]}{1 - r}}$$
(C -2)

where

$$r = P_2/P_1$$

is the ratio of the upstream static pressure to the downstream ambient pressure. By measuring the static pressure upstream of the sample in the plenum chamber the pressure differential across the orifice was known. The diameter ratio,  $\beta$ , was calculated as the ratio of the upstream diameter,  $D_1$ , to the effective diameter of the sample apertures where effective diameter was calculated as the diameter of a single orifice of area  $A_2$ . Sufficient flow was supplied to the sample apertures to produce velocities of the same magnitude as the peak velocities obtained in the high frequency tests. A list of the flow coefficient and the velocity range over which they were measured appears in the table below.

σ	t in.	Minimum Velocity ft/sec	Flow Coefficient	Maximum Velocity ft/sec	Flow Coefficient	Average Flow Coefficient
1.5	0.10	433	0.68	447	0.70	0.69
3.0	0.10	447	0.76	493	0.71	0.73
3.95	0.09	443	0.86	519	0.86	0.86
5.65	0.09	334	0.86	456	0.84	0.85
6.95	0.10	284	0.67	<b>34</b> 9	0.67	0.67
8.00	0.10	293	0.68	<b>3</b> 84	0.68	0.68
8.85	0.10	242	0.61	325	0.60	0.61
10.8	0.10	301	0.93	<b>3</b> 48	0.91	0.92
13.0	0.10	276	0.85	290	0.81	0.83
5.4	0.05	363	0.70	430	0.66	0.68
5.4	0.10	356	0.78	424	0.78	0.78
5.4	0.15	340	0.71	410	0.71	0.71
5.4	0.20	311	0.60	381	0.64	0.62
5.4	0.25	337	0.68	405	0.69	0.69

#### APPENDIX D ACOUSTIC DATA

Acoustic data obtained under the present program are listed in the following tables. For simplicity, the IBM printouts from the data reduction deck are used.

A brief title describing the type of data precedes each individual listing. Next the properties of the gaseous medium and the dimensions of the resonator assembly that are input into the deck are listed. The following list identifies each header.

DEN Density (Cavity Gas),  $1b_m/ft^3$ 

SONIC Sonic Velocity (Cavity Gas), ft/sec

VIS Dynamic Viscosity (Cavity Gas), 1b<sub>m</sub>/ft/sec

CF Flow Coefficient

SIG Open Area Ratio

XL Cavity Backing Distance, in.

T Liner Thickness (aperture length), in.

D Aperture Diameter, in.

Then a listing of the experimental data and results follows:

Data FREQ Frequency, Hz

PA1 Chamber Pressure Amplitude RMS,  $1b_f/in^2$ .

PA2 Cavity Pressure Amplitude RMS, 1b<sub>f</sub>/in<sup>2</sup>

PHASE Phase Angle, deg

Results INERT Specific Acoustic Inertance

REACT Specific Acoustic Reactance

RESIS Specific Acoustic Resistance

IMPED Specific Acoustic Impedance

ABSOR Absorption Coefficient

SPL Incident Pressure Amplitude, db

# **Pratt & Whitney Aircraft**

PWA FR-3299

Nonlinear Correction Term DNLD Particle Velocity in Apertures, ft/sec UORF Effective Length of Aperture, in. LEFF K<sub>2</sub> Resistance Proportionality Coefficient = K2RES RESIS  $\sigma_{\rm cC_f}^2$ /UORF Comparison of Nonlinear Correction Term with DNLDK Sirignano Theory Velocity of Steady Flow-Through the Aperture, ft/sec VELTH VELPT Velocity of Steady-Flow Past the Apertures, ft/sec

DATA USED IN THE HIGH FREQUENCY ANALYSIS

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SCNIC

DEN

RESONATOR CONFIGURATION NO. 1

5.24 0.169 1.51	6.60 0.168 1.25 8.40 0.166 1.04 10.70 0.165 0.86 13.48 0.163 0.75 16.20 0.163 0.70	6.60 0.168 1.25 8.40 0.166 1.04 10.70 0.165 0.86 13.48 0.163 0.75 16.20 0.163 0.75 20.88 0.161 0.58 25.98 0.158 0.53 31.96 0.155 0.49 37.56 0.154 0.49	6.60 0.168 1.25 3.51 8.60 0.166 1.04 3.35 10.70 0.165 0.86 2.87 13.48 0.163 0.75 2.59 16.20 0.165 0.70 2.59 20.88 0.161 0.58 2.09 25.98 0.159 0.49 2.00 37.56 0.155 0.49 2.07 44.13 0.151 0.48 2.09 58.84 0.149 0.47 2.12 77.57 0.149 0.46 2.08
			200 200 200 200 200 200 200 200 200 200
			119.00 121.08 123.17 125.22 127.37 129.52 131.66 133.76 135.76 139.65 143.47
			0.000000000000000000000000000000000000
			9 4 4 6 6 6 6 6 6 7 7 8 8 8 8 8 8 8 8 8 8 8 8
0.999 1.041	1.165	1.02 1.05 1.05 1.05 1.05 1.05 1.05 1.05 1.05	11 12 14
2.673 2.657 2.657	2.50 2.50 2.50 2.50 2.50 2.50 2.50 3.50 5.50 5.50 5.50 5.50 5.50 5.50 5	2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	11 12 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
6.267 6.251 6.191	6 1 1 2 8 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	6 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	1444 1444 1444 1444 1444 1444 1444 144	2000 2000 2000 2000 2000 2000 2000 200	
000 000 000 000	0.007	0.007 0.007 0.0011 0.0018 0.022	00000000000000000000000000000000000000
			0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
1200.0	000		12000000000000000000000000000000000000

	RESONATOR CONFIGURATION NO.	R CONFIG	URATION	NO. 2	:									
DEN	SONIC	2	VIS	P.	816	×	þ	۵						
0.0750	1129.0	0.1220	0.12200E-04	0.730	0.0300	0.500	0.100	0.056						
FREO	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLDK
0	0	700.0	152.7	0.010	2.03	0.44.0	1.04	0.613	115.80	1.69		0.164	٦.	3.09
	700 T	0.00	157.8	3.803	0.928	0.477	0	0.627	117.85	1.83	9.02	•	0.95	2.58
0.004	400	0.012	151.4	3.802	0.927	0.505	•	0.646	119.94	2.10	ä	0.164	0.81	2.28
1500.0	į	0.015	140.3		0.897		1.04	0.675	122.08	2.37	•	•	0.67	1.94
1500-0	70000	0.00	144.8	•	0.862	0.608	1.05	0.730	124.36	3.10	-	0.161	0.61	1.90
1500.0		0.024	140.8	3.722	0.847	0.690	1.09	0.772	126.61	3.90	-	• 16	0.57	1.86
150000		0.029		3.692	0.818	0.762	1.11	0.807	128.84	4.59	56.64	• 15	0.51	1.73
150000		0.035	133.4	3.679	0.804	0.850	1.17	0.835	131.04	5.45	2	• 15	0.47	1.66
0.0021		0.043	128.2	•	0.741	0.941	1.19	0.872	133.34	6.33	_	.15	0.43	1.53
000	i	0.052	122.5	3.557	0.682	1.070	1.26	0.901	135.62	7.57	•	.15	0.41	1.51
		0.059	119.1	3.551	0.676	1.216	1.39	906.0	137.67	8.98	•	• 15	0 * 0	1.53
1500.0		0.078	112.1	3.504	0.629	1.550	1.67	0.898	141.59	2.2	•	.15	0.39	1.53
1500.0		660.0	107.3	3.501	0.626	2.011	2.10	0.850	145.15	9.9	•	• 15	0.40	1.63
1500-0		0.126	103.8	3.500	0.625	2.546	2.62	0.785	148.69	1.8	•	. 15	0.40	1.65
1500.0		0.164	101.0	3.483	0.608	3.130	3.18	0.718	152.30	7.5	48.	.15	0.38	1.56
1500.0	0.29	0.207	98.7	3.482	209.0	3.968	4.01	0.633	155.88	35.62	86.	. 15	0.38	1.62
1500.0	Ö	0.258	96.2	3.427	0.552	5.082	5.11	0.545	159.52	6.4	32.		0.39	1.68
1500•0	0	0.321	95.2	3.465	0.590	6.484	6.51	0.460	163.21	59.97	•	. 14	0.40	1.74
1500.0	1.15	0 • 395	95.2	3.635	0.760	8.353	8 • 38	0.379	166.95	78.07	ຮູ	•	0.42	~ ·
1500.0	1.265	• 40	95.2	3.680	0.805	8.847	8.98	0.362	167.70	82.86	•	0.158	0.43	7.65

			DNLOK	1.01	1.07	1.09	1.12	1.05	1.17	1.18	1.03	96.0
			KZRES D	0.39	0.39	0.39	0.39	0.35	0.39	0.39	0.34	0.31
			LEFF	0.122	0.121	0.121	0.121	0.118	0.119	0.127	0.131	0.121
			UORF	68.44	86.16	109.73	138.14	182.10	218.94	275.62	371.81	473.50
			DNLD	6.67	9.29	12.28	16.25	20.17	27.46	35.17	41.77	49.77
			SPL	138.78	143.31	146.80	150.08	153.53	156.80	160.28	163.97	167.21
	۵	0.052	ABSOR	0.977	.0.993	0.978	0.938	0.892	0.802	0.715	0.653	0.593
	-	060.0	IMPED	0.83	1.04	1.30	1.63	1.96	2.59	3.26	3.84	4.51
	×L	0.500	RESIS	0.807	1.032	1.289	1.630	1.967	2.593	3.255	3.822	4.509
	516	56É0°0	REACT	0.193	0.165	0.174	0.162	0.103	0.126	0.296	0.374	0.173
£ • 03	A)	0.864	INERT									2.569
RATION N	v	10E-04	PHASE	103.5	99.1	7.76	7.56	93.0	92.8	95.2	95.6	92.2
CONF 1GU	VIS	0.12200E-04	PA2	0.083	0.105	0.134	0.168	0.222	0.267	0.136	0.454	0.578
RESONATOR CONFIGURATION NO.	SONIC	1129.0	PA1	0.029	0.045	0.072	0.115	0.182	0.290	0.459	0.728	1.089
<b>℃</b> .	DEN	0.0750	FREC	1800.0	1800.0	0.0081	1800.0	1800.0	1800.0	1800.0	1900-0	1,000.0

	RESONATOR CONFIGURATION NO.	R CONFIGI	JRAT ION	4 • 0	:		!							
į	,		9	,	,	:								
DEN	SONIC	>	۸IS	t	SIG	×	-	۵			•			
0.0750	1129.0	0.122	0.12200E-04	0.780	0.0540	0.500	0.100	0.052					•	
FREG	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLDK
2000-0	0.002	0.010	155.5	2.709	. 55	0.252	09•0	0.538	115.49	0.88	6 • 84	0.157	•	2.62
2000-0	0.003	0.012	155.1	2.713	0.557	0.258	0.61	0.546	117.52	66.0	8.51	0.158	1.12	2.22
2000.0	400.0	0.016	154.5	_	.55	0.264	0.61	0.555	119.56	1.07	~	0.157	•	1.84
2000-0	0.005	0.020	153.5	$\mathbf{a}$	.53	0.268	09.0	0.565	121.60	1.12	13.81	0.156	•	1.46
2000.0	2000	0.026	151.8	m	• 52	0.283	09•0	0.588	123.69	1.36	3	0.156	•	1.29
2000.0	600.0	0.031	149.3	2.690	.53	0.317	0.62	0.628	125.86	1.87	21.14	0.156	•	1.29
2000-0	0.011	0.039	144.3	'n	.51	0.367	0.62	0.689	128.15	2.62	G	0.155	•	1.31
2000.0	0.014	0.050	138.6	~	949	0.411	0.62	0.744	130.44	3.29	S	0.152	•	1.22
2000.0	0.018	090.0	134.1	$\circ$	• 45	0.467	0.65	0.792	132.74	4.14	40.29	0.151	•	1.21
2000.0	0.023	0.073	129.7	Œ	• 43	0.518	0.67	0.832	135.02	4.91	49.01	0.150	•	1.15
2000.0	0.029	0.087	128.6	$\circ$	77.	0.558	0.71	0.850	137.15	5.51	$\sim$	0.151	•	1.06
2000.0	0.045	0.118	118.4	i	•39	0.737	0.83	0.928	141.93	8.23	78.57	0.148	•	1.11
2000.0	0.072	0.153	111.3	$\sim$	.37	0.950	1.02	0.964	146.50	11.44	102.39	0.147	•	1.15
2000.0	0.115	0.200	106.0	0	• 34	1.192	1.24	896.0	150.58	15.11	133.44	0.145		1.15
2000.0	0.182	0.255	102.3	ar.	• 32	1.508	1.54	0.942	154.13	19.88	169.93	0.144	•	1.17
2000.0	0.290	0.325	98.8	5	• 29	1.899	1.92	768.0	157.55	25.79	216.41	0.142	•	1.17
2000.0	0.459	0.414	96.5	N	.27	2.376	2 • 39	0.828	160.99	33.00	275.60	0.141	•	1.17
2000.0	0.728	0.527	95.4	2.436	• 28	2.963	2.97	0.750	164.48	41.88	350.98	0.141	•	1.16
2000-0	1.052	0.434	9.46	444	• 28	3.566	3.57	0.681	•	51.00	0	0.142	•	1.17

			LEFF KZRES DNLDK	0.128 0.40 1.03	0.41	0.39	0.36	0.37		000	V	0.37	0.42	
			UORF	66.34										
			DNLD	00.9	8.58	11.30	14.24	10.26	200	25.34	33.07	40.84	40.66	200
			SPL	137,82	142.70	147.39	151.41	154 55	10000	157.76	161.07	164.60	164.21	17.001
	۵	0.047	ABSOR	0.919	76.0	700.0	400		0.00	0.913	0.840	0.770	101	10.00
	-	060.0	IMPED	0.59	0.75	0.00	1.1		1040	1.83	2 • 33	2.83		3.40
	×	0.500	RES1S	775.0	777		1	4 4 4	1.436	1.830	2.330	2.833		3.404
	516	0.0565	REACT	0.158	011.0	21.0	100	- KO • O	0.055	0.012	0.040	0 8 0		-0.148
N •	ñ	0.850	INERT	2.211	27.0	7.1.7	2 100	061.7	2.108	2.066	2.012	1.044	100	1.904
URATION	V I S	0.12200E-04	PHASE	105.3										87.5
CONF 16	>	0.122	PA2	000	10.0	0.163	1910	717.0	0.261	0.325	70740		40.00	0.552
RESONATOR CONFIGURATION NO.	SONIC	1129.0	PA1	0	27000	0.043	7/000				0.4.4.0			0.917
-	DEN	0.0750	FREO		0.0017	2100.0	2100.0	2100.0	2100.0	2100.0	2100.0		0.0017	2100.0

LEFF 52.40 69.54 90.54 115.31 146.85 162.88 184.87 232.74 267.22 306.82 UORF 39.29 43.36 54.00 137.87 147.25 1151.35 1151.35 1154.66 1155.36 161.23 162.99 165.50 0.052 0.859 0.923 0.993 0.993 0.944 0.925 0.925 0.100 0.61 0.73 0.89 1.11 1.61 1.61 0.500 0.589 0.723 1.108 1.384 1.610 1.747 2.200 2.412 2.967 × -0.019 -0.021 -0.072 0.167 0.127 0.122 0.101 0.081 0.003 0.0695 2.221 2.195 2.195 2.175 2.135 2.099 2.099 2.034 2.032 1.981 0.672 RESONATOR CONFIGURATION NO. 1005.9 1001.1 98.2 96.3 94.2 92.9 91.5 89.5 89.5 88.6 0.12000E-04 0.428 0.097 0.128 0.112 0.270 0.340 0.340 0.029 0.045 0.045 0.115 0.182 0.235 0.290 0.459 0.578 0.817 SONIC 1129.0 2100.0 2100.0 2100.0 2100.0 2100.0 2100.0 2100.0 2100.0 2100.0 0.0750 DEN

1.662 1.662 1.662 1.663 1.665

K2RES

1.67

0.33

	RESONATOR CONFIGURATION NO.	יסואד זפן	NOT LAND	• 0										
DEN	SONIC	>	V 1 S	F.	516	х	-	٥						
0.0750	1129.0	0.122	0.12200E-04	0.684	0.800	0.500	0.100	0.056						
FREG	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLDK
0.0000	2000	0.015	147.0			0.196	0.36	0.516	115.41	1.42	7.78	0.177	1.06	3.11
2200.0	0000	0.018	146.0			0.211	0.37	0.539	117.50	1.74	9.35	0.178	0.95	2.93
2200.0	700°C	0.023	144.8	2.272	0.312	0.220	0.38	0.555	119.56	1.93	11.64	0.178	0.19	2.52
2200.0		0.029	142.9	. ^		0.233	0.38	0.577	121.64	2.21	14.48	0.177	0.68	2.21
2200.0		0.035	140.0			0.257	0.40	0.614	123.80	2.72	17.61	0.177	0.61	2.11
2200.0		440.0	134.5			0.285	0.40	0.659	126.00	3.33	22.18	0.175	0.54	1.95
2200.0		0.053	127.9	$\sim$		0.334	0.42	0.723	128.33	4.38	26.36	0.174	0.53	5.04
2200.0		0.065	123.1	_		0.363	0.43	0.759	130.53	2.00	32.43	0.172	0.47	1.84
2200.0		0.075	120.0	ഹ		0.411	0.47	0.803	132.81	6.04	37.23	0.172	94.0	1.89
2200.0		0.091	116.7	മ		0.439	64.0	0.829	134.99	6.64	45.28	0.171	74.0	1.68
2200.0		0.106	112.8	· ·		0.492	0.53	0.867	137.30	7.75	52.59	0.169	0.39	1.66
2200.0		0.143	106.5	ന		0.601	0.62	0.926	141.91	10.10	70.95	0.167	0.35	1.56
2200.0		0.180	102.5	ഹ		0.770	0.78	76.0	146.70	13,73	89.32	0.167	0.36	1.64
2200.0		0.233	101.2	- +		0.952	16.0	066.0	151.17	17.63	115.07	0.168	0.34	1.61
2200 0		0 • 300	98.4	~~		1.182	1.19	0.986	155.05	22.54	148.24	0.167	0.33	1.58
2200-0		CAL 0	9.46	or.		1.481	1.48	0.959	158.41	28.97	188.79	0.163	0.33	1.58
2200.0		0.475	92.3	ന		1.892	1.89	<b>706.0</b>	161.65	37.76	234.95	0.159	0.34	1.64
2200.0	0.498	0.498	92.3	2.03R		1.958	1.96	0.894	162.25	39.19	246.02	0.159	0.33	1.63
				-										

	RESONATOR CONFIGURATION NO.	R CONFIG	URATION	80 • OX	."		:				1	,		
DEN	SONIC	>	V1S	U	516	×	•	٥						
0.0750	1129.0	0.122	0.12200E-04	0.607	0.0885	0.500	0.100	0.047						
FREG	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLDK
6	6	711.0	0.7.0	1,000	3,0	0.452	64.6	0.856	137.20	7.26	55.68	0.153	0.29	1.53
2350	620.0	0.157	0 4 0 4	1.879	440	0.53	0.0	906.0	141.68	9.12	75.12	0.152	0.26	1.39
2360.0	0.010		4.60	1.874	0.039	0.665	99.0	0.959	146.39	12.15	95.66	0.152	0.25	1.41
2350.0		0.258	4.00	1.869	0.034	0.818	0.81	0.989	151.16	15.68	123.24	0.151	0.24	1.39
2450.0	0.145	0.286	92.4	1.874	0.038	0.929	0.93	0.998	153.64	18.22	136.70	0.152	0.25	1.45
7450.0	0.182	0.317	92.5	1.881	0.046	1.054	1.05	966.0	155.70	21.10	151.62	0.152	0.25	1.50
24.00.0	0.235	0.356	95.6	1.890	0.054	1.211	1.21	066.0	157.38	54.69	170.12	0.153	0.26	1.56
2450.0	0000	0.400	92.2	1.886	0.051	1.328	1.32	0.979	158.84	27,39	190.88	0.153	0.25	1.53
2250.0	0.365	0.454	91.7	1.878	0.043	1.473	1.47	0.963	160.47	30.73	216.65	0.152	0.25	1.51
2350.0	0.459	0.521	90.3	1.843	0.008	1,616	1.61	776.0	162.16	34.01	248.75	0.149	0.23	7. 5.
2350.0	0.578	0.585	89.3	1.812	-0.022	1.813	1.81	0.916	163.79	38.54	279.10	0.147	0.23	1.46

	re some of	RESONATOR CORFIGURATION NO.	CKA LICK	• 00		٠								
DEN	SONIC	>	۷IS	Ą.	516	×	-	۵						
0.0750	1129.0	0.122	0.12200E-04	0.916	0.1080	00.500	0.100	0.052						
FRFO	PAl	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	K2RES	DNLDK
2450.0		0.723	136.2		0.156	0.149	0.21	0.445	115.16	1.20	09.6	0.182	1.59	2.42
2450.0		0.00	134.6	-	0.150	0.152	0.21	0.451	117.18	1.27	12.22	0.181	1.27	1.96
2450.0		0.037	133.0	-	0.145	0.156	0.21	0.460	119.21	1,39	15,39	0.181	1.04	1.63
2450.0		0.047	130.R		0.141	0.163	0.21	0.476	121.27	1.59	19.15	0.180	0.87	1.42
2450.0		0.058	127.6		0.133	0.173	0.21	0.497	123.34	1.86	23.84	0.180	74.0	1.26
2450.0		0.071	123.1	7	0.123	0.189	0.22	0.530	125.46	2.31	28.99	0.179	0.67	1.20
2450.0		0.045	116.3	-	0.105	0.212	0.23	0.574	127.63	2.94	34.86	0.177	0.62	1.19
2453.0		0.105	107.P	-	0.074	0.231	0.24	0.608	129.77	3.45	45.89	0.174	0.55	1.09
2450.0		0.126	104.1	-	0.061	0.246	0.25	0.633	131.88	3.87	51.56	0.173	0.48	66.0
2450.0	0.023	0.147	101.5	1.815	0.054	0.270	0.27	0.668	134.05	4.52	59.89	0.172	94.0	0.97
2450.0		0.153	103.3	1:	0.076	0.322	0.33	0.735	136.39	5.97	62.71	0.174	0.52	1.17
2450.0		0.207	97.9	-	0.053	0.385	0.38	0.802	140.80	7.71	84.60	0.172	94.0	1.∙ ଠ8
1450.0		C.261	64.7	ŗ	0.040	0.488	67.0	0.881	145.42	10.54	106.51	0.171	94.0	1.14
2450.0		0.336	95.6	1:	0.027	0.602	0.60	0.938	150.07	13.69	137.21	0.169	74.0	1.12
2450.0		0.433	60 و ه	;	0.010	0.742	0.74	0.978	154.80	17.53	176.76	0.168	0.42	ា • T
2450.0		0.540	89.C	:	-0.016	0.945	<b>76.0</b>	666.0	159.74	23.12	219.98	0.165	0.43	1.15

	·	S DNLDK	31	90	84 1•	71 1.	62 1.	57 1.	24				70	• •	90	• • •	32	32 0.	31 C•	29 O.	29 0•	28 0.	27 0.	
		KZRE	7		• •	•	°	• •		00		•	•	5	•	•	o ·	å	•	• •	•	•	9	
		LEFF		0	0	0	0	0	0	96	<b>9</b> C	•	2 (	<b>O</b>	0	0	0	O	0	0	0	0	0	
		UORF	11.16	13.8	17.4	21.26	25.56	30.03	34.4			200	000	40.00	1000	111.60	128.1	142.13	163.16	189.5	215.1	244.1	277.1	
		DNLD	1.76	1.81	1.80	1.96	2.20	2.58	3.09	F		9 6	200	6.98	7.89	Ġ	ċ	÷	ë	14.88	Ļ	æ	<b>.</b>	
		SPL	115.14	117.16	119.15	121.19	123,25	125.33	127.45	150.51		133.00	135.93	140.27	142.65	144.67	147.00	149.19	151.43	153,66	156.19	158,21	160.45	
٥	0.052	ARSOR	0.440	444	0.443	4	4	4.	č.	245	•	٠,	١٠	•	•	`	8	8	8	ς.	6	5	٠,	
<b>-</b>	0.100	IMPED	~	0.15	7	∹	7	∹	7	7	~ •	7	~	ū	£.	<u>۾</u>	4	4	S.	S	9			
×	008.0	RESIS	0.14	ŏ	ō	ō	ċ	Ö	ŏ		ċ (	Ö	ċ	Ö	ŏ	ō	ŏ	ċ	č	ŏ	ŏ	ŏ	Ğ	
516	0.1300	REACT	-0.054	-0.056	-0.056	-0.058	-0.060	-0.064	-0.072	-0.082	0.0	-0.095	-0.070	-0.092	-0.106	-0.120	-0.135	-0.150	-0.160	-0.168	-0.194	-0.208	-0.233	
OF	0.831	INERT	0	0	1.601	O.	1.597	1.594	• 58	~	. 9	• 56	• 58	S	5	1.537	N	0	640	49	46	1.450	1.425	
V15	0.12200E-04	PHASE	69.2	0.69	68.7	68.7	0.69	69.3	6.89	67.0	69.7	9 • 9 9	74.5	73.2	72.3	71.9	711.7	71.9	72.4	73.0	72.7	72.9	72.7	
>	0.122	PA2	03	0.038	0.048	0.059	0.071	٠ د د د	60.	0.114		• 15	. 18	• 23	۴.	0.310	0.356	0.395	0.454	55.	50	67	77.	
SONIC	1129.0	PA1	0.002	0.003	<b>700.0</b>	0.005	0.007	600.0	0.011	0.014	0.018	0.023	0.029	0.045	0.059	0.072	0.092	0.115	0 145	0.187	0.035	0.290	0.365	
DEN	0.0750	FREO	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	2600.0	260040	2400.0	2600.0	0.0042	0.0046	2600.0	

		DNLDK	1.12	. ~		4	4	4	4	.5	Ŋ	3	1.87	8	۲.	9.	ŝ	3	<b>ب</b>	٠.	• 2	ď	•	٥.	8	•	Š
		KZRES	0.24	. ~	.2	•,7	• 2	•5	• 2	• 2	4	4	0.37	.3	6		6	٠.	• 5		• 2		7	7	7	٦.	7
		LEFF	0.104	6	60	•00	•00	• 08	60.	60•	10	.10	0.071	.08	• 08	60.	60.	•08	60.	60.	•00	60•	60.	90.	•08	• 08	•08
		UORF	68.54	06.1	5.0	29.1	43.2	9.09	80.2	6.66	21.8	8.8	74	10.7	45.6	73.1	9 • 68	0.86	07.5	04.8	8*66	85.2	90.7	84.4	70.8	9.0	43.4
		DNLO	6.51	2	9	6.7	5.5	1.8	4.7	8,3	2 • 4	9	23.59	9.1	2.2	3.1	1.5	9.3	5.5	3.0	0.0	0.6	5.1	1.8	٦.	7	۲.
		SPL	138.21	7.04	49.5	51.1	52.6	54.3	55.9	57.5	59.2	6.09	154.52	55.0	55.8	56.6	57.2	57.5	57.6	57.3	56.9	56.5	56.3	55.9	55.4	55.1	54.7
۵	0.052	ABSOR	0.926	0 0	66.	.97	• 95	• 93	• 90	• 86	. 82	7.8	0.108	30	.54	• 73	.82	•86	•86	.83	• 78	.71	99.	• 56	• 45	.33	•21
<b>j</b>	0.050	IMPED	0.62	0 0	7	6	5	•	8	7	4	-	5.83	œ	6	4	.2	~	•	∹	٦.	6	• 2		ē.	9	0
×	0.500	RESIS	0.601		17	.32	.50	• 6 A	.89	.15	4	7.3	666.0	4.5	.82	.07	.15	.16	.03	•95	.81	.78	.51	.28	0.0	.82	09•
816	0.0540	REACT	0.181	9 0	.08	.07	•06	•06	.07	• 08	111	16	5.7	.60	2.32	1.36	69.0	0.15	•39	•76	• 16	.48	•65	.95	.27	.54	. 93
P.	0.676	INERT	0.5	1.972	96	.95	• 94	•94	• 94	• 95	66	C	0.431	70	66.	.33	.57	.80	. 12	.30	.55	• 79	.86	40.	.27	46	α.
S	.12200E-04	PHASE	9	99.0		9	2	2	2	5				2	æ	•	2	5	010	11.	22.	29.	37.	46.	54.	62	168.3
>	0.1220	PA2	80	901.0	.15	.16	. 18	.21	. 23	• 26	29	. 6	0.317	33	33	32	30	.27	.24	21	19	.16	15	. 14	-	07.	ردا
SONIC	1129.0	PAl	03	7 40 ° 0	6	.1	.15	.18	. 23	•		1 7		0	9.0	30	30	30	30	30	30	30	30	9	90	•	ະຕ
DEN	0.0750	FREG	300	2300.0	000	300	300	300	300	300	300	' '	700	•	000	9009	000	200	500	800	100	300	009	950	300	007	5100.0

RESONATOR CONFIGURATION NO. 11

D-13

	RESONATOR	ESONATOR CONFIGURATION NO.	URATION	NO. 12										
					•		-	:						
DEN	SONIC	>	۷۱۶	Ą	816	۲ĸ	<b>-</b>	٥		٠				
0.0750	1129.0	0.122	0.12200E-04	0.710	0*60*0	005 •0	0.150	0.052			-			
FREG	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	K2RES	DNLDK
1700.0	9000	0.092	_	06	36	-	-	.92	37.9	7.67	4	• 19	4	
1700.0	0.045	0.122	110.2	86	32	8	0	96	3.	0	7	• 19	e.	•
1700.0	0.072	0.163	_	.83	29	0	-	.97	46.8	4	7	• 19	٠.	•
1700.0		0.185		.82	28	7	~	.97	48.6	16.18	9	• 19	e.	•
1700.0		0.207	-	.81	.27		÷	•96	50.4	0	4	• 19	e.	•
1700.0	0	0.235	_	.80	.26	€.	10	•94	52.1	~	~	• 19	e.	•
1700.0	0	• 26	-	.79	.25	7	-	.91	53.8	4	ď	• 19	ď.	•
1700.0	0	0.303	_	• 76	.23	٥.	0	•89	55.5	~	ó	• 18	e.	•
1700.0	0	0.336		• 76	.22	7	~	• 85	57.2	7	4	• 18		•
1700.0	0	0.377	•	74	.20	4	•	.82	58.9	9	9	. 18	٠.	•
1700.0	0	0.433		.72	1.18	9	•	• 78	60.7	0	ē	• 18	٠	•
1700.0	0	0.552		68	.15		E.	5.	64.2	0	ū	• 18		•
700.0	C	ູ	12.8	.27	.88	~	0	• 15	e.	4	ō	.21	4	•
1000.0	0	.40	•	.71	99	9	0	• 48	55.2	~	9	• 19	e.	•
1200.0	0	4.1	•	.02	56	6	5	69•	56.2	す	ď	• 19	٠.	•
1400.0	0	•	•	. 32	.75	7	~	•82	56.9	4	7	• 19	٠	•
1600.0	0	.35	_	.61	.0	7	_	•86	57.2	e	Œ	• 19		•
1700.0	0	• 59	-	.57	40.	2	~	96•	59.1	Q	9	• 17	٦.	•
1800.0	0	.31	2	.87	47	7	-	• 84	57.1	0	ď	. 18	e.	•
2000.0		.27	8	.22	•06	6	~	• 78	56.7	•	7	• 18		•
2300.0	0.2	.22	5	58	.7	۲.	3	•66	56.0	0	∹	. 18		•
2600.0		0.168		08	.42	4	8	640	55.3	S	٥	• 18	۳,	•
2900.0	0.2	•	158.8	4.520	3.033	1.176	3.25	0.337	154.82	10.88	127.83	0.181	0.28	1.06
3200.0		0.110	164.9	Q	• 42	٥.	S.	• 23	ຮ	7.15	٠	• 17	?	•

			DNLOK	.3	2.38	• •	ļ	6		e.	<b>.</b>	9	• 2	.2	÷.	e.	'n	4	٦.	<b>.</b>	ω,	?	٦.	7	7	٦.	٦.	~	2.	۲.	6.	3
			KZRES	1	74.0	1 1	t ·	4	4	4	4.	4	.3	٩.	۳.		ď	.3	4	1	4		.3	6	~	.3	3	e	ď	.3	۳,	۵.
			LEFF	.28	0.276	. 27	26	• 26	• 26	• 26	• 26	• 26	.25	.25	• 25	• 25	.25	.27	.25	.25	• 25	• 25	• 25	• 26	• 25	• 25	•26	• 26	.25	•26	.26	• 25
			UORF	3.1	56.28		1 4	07.2	0.3	35.0	53.2	73.9	97.4	21.5	48.5	78.8	12.8	55.1	84.9	01.7	18.4	34.6	48.1	56.1	57.8	60.4	58.6	48.5	42.2	9.2	11.1	7.5
			DNLD	1.6	15.84	, a	6.7	0.1	4.5	9.3	4.1	9.5	5.4	2.8	1:1	0.3	0.7	2.3	3.8	8.4	2.2	3.6	3.9	<b>7. • 7</b>	3.9	1.9	9.8	5.5	8.8	2.0	0.0	4 • 2
			SPL	38.6	142.92	400	49.8	51.5	53.2	6.49	56.7	58 • 4	60.2	62.0	63.8	65.6	67.4	69.4	54.4	54.8	55.2	55.7	56.2	56.5	56.7	56.8	56.7	56.2	55.8	55.3	6.45	54.6
	Ω	0.052	ABSOR	.97	0.982	9 4 5	.92	.89	•86	• 82	• 78	• 74	• 70	• 66	•62	• 57	• 53	64.	.21	.33	.47	• 60	69•	• 76	• 79	• 90	• 78	.71	•62	• 4 A	.33	• 56
	<b>-</b>	0.200	IMPED	6	1.17	ı ıc	, <b>^</b> -	0	7	4.	7	Ç		۲.	. 2	۷.	• 2	Ć.	80	Ç	÷ 5	0	œ.	Ÿ	9	J.	÷	۲.	o.	.2	۲.	. 2
	×	004-0	RESIS	.91	1,145	• • • • • • • • • • • • • • • • • • •	17.	.93	- 1 -	77.	.71	00.	.33	• 74	• 2 C	.71	• 50	• 63	.51	• B 1	ر د د	• 56	• 30	• 52	• 60	• 59	• 56	77.	•16	.82	• 76	• 43
	516	0.0540	REACT	.31	0.245	16	• 15	.13	.10	• 0.8	.07	.05	• 0.2	00.0	00.	00.	• 03	• 20	4.65	• 66	2 • 8 2	5.09	1.47	0.84	0.42	.01	• 56	.32	96.	•65	62.	• 01
0 N O N	CF	0.618	INERT	.39	3.325	24	23	.21	1.9	.16	.15	.13	• 10	۲ر.	7.	α.	. 11	• 28	. 50	.72	96•	.23	7:,•	7.4	9 g	6∵•	• 43	a.	. 23	• 70	• 17	.47
CONFIGURATION 1	15	00E-04	PHASE	•	102.1	• •		÷	٠,	5		-	ċ	Ġ	6	ပံ	ċ	5	æ	ċ	•	7	ď	÷	ċ	ů	05.	ι α	32.	Š	5.	٠ د د
	>	0.12200	PA2	60	0.120	1 4	20	.23	• 25	• 29	.32	72.	.42	47	• 53	• 59	67	• 76	• 36	α (3)	• 30	0.40	Ŭ <b>7</b>	930	• 36	• 34	31	ر. دع	• 2.5	₫	7.	Ξ.
RESONATOP	SONIC	1129.0	PA1	Ç	0.045		7	~	7	?	?	ď.	7	ur:	•	Ġ	7	7	5		۲.	3	7	ç.		·	`:				•	•
_	0 FR	0.0750	F R E O	•005	1400.0	000	400	•004	007	40C+	40C+	400	<b>4</b> 00	400	•00,	<b>•</b> 00 <b>•</b>	<b>•</b> 00 <b>•</b>	<b>•</b> 00 <b>•</b>	00	00	<b>.</b> 006	000	100	20v.	30¢	•007	٠ د د د د	<b>1</b> 00	• ∪06	00	• JUE	• 009

D-15

RESONATOR CONFIGURATION NO. 14

		DNLOK	80		9		•	•	•	•	•	8	٠.		8	8	8	8	4	8	•	8		•	۲.	٠,		8	. 7	•	
		K2RES (	.5	4	4	643	<b>.</b>	•	<b>*</b>	<b>:</b> :	*	4	Ü	4	۳.	÷	ď	ď		4	4	4.		e.	٠	.3	4	4	4	6	
		EFF	.32	.31	.31	0.315		100	9	•	٠ د	• 30	• 58	• 29	• 28	• 28	•27	• 29	.31	.30	•29	.33	.30	30	30	• 29	• 30	.30	.30	.30	30
		UORF		•	•	92.93	• • •	D (	•	,,,	•	91.	20.	41.	77.	11:	45.	91.	93.	•	11:	34.	54.	6	73.	73.	69	62.	•	29.	13.
		DNLD	0.1	3.5	8.0	20.46	3.7	٠ •	֡֟֝֟֓֓֓֓֓֓֓֓֓֟֟֓֓֓֟֟֓֓֓֟֓֓֓֟֟֓֓֓֟֓֓֓֟֓֓֓	• •	\ · · 6	5.3	0.2	8.5	4.7	3.3	0.4	3.9	1.6	9.0	4.2	7.7	9.1	9.3	0.3	9.2	7.1	4.5	7.7	2.2	4.6
		SPL	38.5	65.24	46.7	148.51	20.1	51.8	53.5	7.00	26.9	58.6	4.09	62.1	0.49	65.8	67.6	4.69	71.3	54.5	6.49	55.4	56.0	56.6	56.9	57.0	56.8	56.5	55.8	55.3	54.7
۵	0.052	ABSOR	96	98	161	96-0	76	92	689	9	.82	. 78	• 75	69	•66	.61	.57	53	.54	.22	.36	.53	•67	.77	.82	. 82	.81	.75	.62	448	32
<b>j-</b> -	0.250	IMPED	0	ó	~	1.41	ผ้	-	٠.	┪.	4	۲.	•	4	۲.	.2	۲.		7	ŝ	-	0	ç	4	4	4	4	3	8	~	9
×	0.500	RESIS	8.	9	.27	1.400	5.7	. 75	- 6	91.	.42	. 72	66.	43	•76	.22	• 79	.31	.19	.36	.67	.93	.10	.21	.36	04.	.37	.31	40.	.80	.38
816	0*00*0	REACT	~	.2	.2	0.199	٦,	7	٦,	•	•	9	0	0	7	7	0.2	0.0	7			4	1.6	0	4.0	0	e.	7	•	9	
P.	0.686	INERT	61	57	53	3.516	40	47	44	. 41	38	36	31	27	.21	15	7	. 28	49	• e5	0.05	37	63	88.	. 16	. 34	6.65	6	.5	.91	43
v	0E-04	PHASE	• 60	103.R	99.	98.1	•		•	<b>.</b>	<b>:</b>	å	ċ		•				٠,		å	æ	ä	ູ້	ě	40.0	03.	15	•	45	
V1S	0.12200E-04	PA2	0.106	0.143	0.1A7	0.214	0.241	0.273	0.307	0.352	0.395	0.444	0.509	0.558	0.641	0.720	0.798	906.0	1.141	0.395	0.419	674.0	0.464	0.464	C • 433	0.400	0.365	0.325	0.258	0.205	0.163
SONIC	1129.0	PA1	0.029	0.045	0.072	0.091	0.115	0.145	0.182	0.230	0.290	0.365	0.459	0.578	0.728	0.917	1.154	1.453	1.78.8	0.290	0.290	0.290	0.290	0.200	0620	0.290	0.50	0.290	0.50	0.290	06.0
DEN	0.0750	FREG	1300•0	1300.0	1300.0	1300.0	1300.0	1300.0	1300.0	1300.0	1300.0	1300.0	1300.0	1300.0	1300.0	1300.0	1300.0	1300-0	30000	700.0	0.008	0.006	1000	1100.0	1200.0	1300.0	1400.0	1500	1700.0	1900-0	2100.0

D-17

	RESONATOR CONFIGURATION NO. 16	CONFIG	URATION	90. 90.	. •									
DEN	SONIC	>	V1S	ħ.	516	×	<b>}-</b>	۵						
0.0750	1129.0	0.122	0.12200E-04	0.916	0.1080	0.150	0.100	0.052						
FRED	PA1	P A 2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNCD	UORF	LEFF	KZRES	DNLDK
1000	660.0	760.0	2.2	0.175	-14.199	0.545	14.21	0.010	144.20	20.61	4.73	0.000	11.78	30.75
2000		0.116		1,380	-5.806	0.641	5.84	0.00	144.43	16.63	11.65	0.160	5.62	
0000		0.174	10.9	2.264	-2.526	0.486	2.57	0.226	144.71	9.19	26.14	0.175	1.90	
3500.0	0.093	0.244	18.8	2.611	-1.495	0.509	1.57	0.451	145.38	8.81	42.60	0.173	1.22	
3900.0		0.348	34.2	2.855	-0.830	0.564	1.00	0.719	146.60	07.6	67.82	0.170	0.85	
4100.0		404.0	48.7	2.969	-0.536	0.610	0.81	0.847	147.33	10.08	82.81	0.168	0.75	
4200.0		0.433	58.1	3.031	-0.391	0.628	0.74	968.0	147.77	10.30	90.90	0.168	0.10	
4300.0		604.0	69.5	3,109	-0.233	0.624	99.0	0.927	146.92	10.01	87.86	0.168	0.72	
4400.0		0.336	81.6	3.185	-0.081	0.555	0.56	0.915	143.78	64.8	73.92	0.168	0.76	
4500.0		0.356	95.5	3.249	0.055	0.571	0.57	0.924	144.79	8.71	80.08	0.168	0.73	
4600.0		0.300	112.4	3.334	0.209	0.507	0.54	0.876	142.58	7.29	68.89	0.168	0.75	
4800.0		0.373	128.4	3.462	0.467	0.589	0.75	0.859	147.43	8 • 6 8	89.45	0.168	0.67	
5000		0.310	144.1	3.578	0.703	0.509	98.0	0.734	146.59	9.90	17.50	0.166	0.67	
5200.0	0.093	0.235	157.6	3.781	1.017	0.419	1.10	0.550	145.74	5.01	61.14	0.169	0.40	

RESONATOR CONFIGURATION NO. 17

	RESONATO	RESONATOR CONFIGURATION NO. 18	SUKATION	0										
•					į		!							
DEN	SONIC	>	٧١٤	P.	516	ᅻ	-	۵۰						
0.0750	1129.0	0.122	0.12200E-04	989.0	0*00*0	0.500	0.100	0.037						
FREO	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLDK
2000		0.091	7.96	2.235	0.079	0.677	0.68	0.960	138.43	6.53	66.09	0.130	0.31	1.17
2000		0.116	6.96	2.258	0.101	0.842	0.84	0.989	143.15	9.03	77.67	0.131	0.31	1.23
2000		0.157	96.1	2.262	0.105	0.991	66.0	0.997	147.54	11.28	104.78	0.131	0.27	1.11
2000		0.200	94.5	2.253	0.097	1.236	1.24	0.986	151.05	15.00	133.44	0.131	0.26	1.14
2000.0		0.258	91.5	2.196	0.039	1.525	1.52	0.956	154.35	19.37	171.90	0.127	0.25	1.12
2000		0.317	90.2	2.163	90000	1.966	1.96	0.893	157.55	26.03	211.48	0.125	0.26	1.21
2000		4040	89.8	2.147	-0.008	2.447	7.44	0.823	160.95	33.30	269.33	0.125	0.26	1.21
2000.0		0.475	89.8	2.144	-0.011	3.301	3.30	0.713	164.27	46.21	316.43	0.124	0.29	1.42
2000.0	1.102	0.620	6.06	2.216	0.060	3.833	3.83	0.656	167.59	54.26	412.36	0.129	0.26	1.27

	200			•										
DEN	SONIC	>	V1S	A.	SIG	×	<b>-</b>	۵						
0.0750	1129.0	0.122	0.12200E-04	0.920	0.0540	00 \$ 00	0.100	760°O						
FREG	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLDK
1900.0		0.116	102,1			0.581		0.924	137.88	7.20	99.90		0.42	1.06
1800.0		0.159	95.5			0.687	69.0	796.0	142.49	8.89	95.39		0.37	0.93
1800.0		0.196	91.9			0.889	0.89	966.0	147.49	12,11	117.36		0.39	1.01
1800.0		770	90.3			1.133	1.13	966.0	151.47	16.00	146.05		0.40	1.05
1800.0		0.303	89.7			1.443	1.44	0.967	154.55	20.94	181.77		0.40	1.09
1800.0	0.290	0.373	89.3	2.373	-0.022	1.859	1.85	606.0	157,71	27.57	223.62	0.153	0.42	1.15
1800.0	0.459	0.475	4.06			2.314	2.31	0.842	161.09	34.82	284.79		0.41	1.13
1800.0	0.728	0.585	91.5			2.980	2.98	0.752	164.49	40.44	350.37		0.43	1.19
1800.0	1.040	0.672	63.6			3.702	3.71	0.667	167.14	56.94	402.28		0.47	1.30

II. DATA AT RESONANCE WITH INCREASING SOUND PRESSURE

750	1130.0	0.122	0.12200F-04	0.780	0.0540	004.00	0.100	0.052	•					
PEO	PA1	PA2	PHASE	INERT	REACT	RESIS	1 MPED	ABSOR	SPL	DNLD	UORF	LEFF	K2RES	DNLDK
24.0	0.029	0.112	0.06		0000-	0.685	0.68	0.965	138.51	7.38	49.09	0.153	0.41	1.32
0	0.051	0.150	0.06		-000	0.905	06.0	0.997	144.57	10.63	81.62	0.150	0.41	1.37
0.47	0.091	0.200	0.06		-0.000	1.189	1.18	0.992	149.28	14.74	110.50	0.146	0.39	1.38
11.0	0.163	0.147	0.06		-0.000	2.834	2 • 83	0.771	151.60	38.83	82.42	0.141	1.27	4.73
24.0	0.290	0 - 348	0.06		-0.00	2.112	2.11	0.872	157.34	28.10	196.66	0.139	0.39	1.45
0.60	0.515	0.440	0.06		-0.00	2.805	2.80	0.774	161.62	38.41	263.42	0.141	0.39	1.46
84.0	0.917	0.612	0.06	2.588	-0.000	3.873	3.87	0.652	165.97	54.50	339.21	0.144	0.42	1.59
39.0	1.154	0.720	0.06		-0000	4.242	4.24	0.617	167.81	99.09	369.93	0.151	0.40	1.52

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SONIC

DEN

DATA AT RESONANCE CONFIGURATION NO. 20

:		DATA AT RESONANCE CONTIGORATION NO. 21	CE CONF.	NOT LAXOS	NO. 71									٠
DEN	SONIC	>	VIS	P.	516	×	<b>-</b>	۵						•
0.0750	1130.0	0.1220	0.12200E-04	0.780	0.0540	009•0	0.100	0.052						
FREO	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLOK
1675.0		0.093	0.06	2.147	-0.000	0.663	99.0	0.959	138.40	8.05	62.61		0.39	1.26
1683.0	0.051	0.129	0.06	2.137	-0.000	0.850	0.85	0.993	144.32	11.11	86.84	0.148	0.36	1.21
1685.0		0.168	0.06	2.134	-0.000	1.159	1.15	766.0	149.38	16.19	113,31	0.147	0.37	1.32
1688.0		0.230	90.0	2.130	-0.000	1.508	1.50	0.958	153,39	21.92	154.89	0.147	0.36	1.29
1692.0		0.296	0.06	2.125	000.0-	2.077	2.07	0.877	157.39	31.25	200.01	0.146	0.38	1.41
1688.0		604.0	0.06	2.130	-0.000	2.682	2.68	0.791	161.73	41.26	275.44	0.147	0.36	1.34
1678.0		0.527	0.06	2 - 143	-0.000	3.725	3.72	0.667	166.04	58.62	352.74	0.148	0.39	1.47
1620.0		0.598	0.06	2.220	-0.000	4.279	4.27	0.614	167.80	69.04	386.53	0.159	0.41	1.55

200														
	SONIC	VIS	v:	R	516	×	•-	۵						
0.0750 113	1130.0	0.12200F-04	10F-04	069.0	008000	0.400	0.100	0.056						
FREG P	PA1	PA2	PHASE	INERT	REACT	RES I S	IMPE	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLOK
2351.0 0.	620	0.19	0.06	2.294	-0.000	0.556	0.55	0.918	137.82	8.77	50.36	0.168	0.47	2.00
	.051	0.166	0.06	2.274	0000-0-	0.102	0.10	696.0	143.60	11.73	70.95	0.165		1.86
	0.091	0.219	0.06	2.261	-0.000	0.942	76.0	666.0	149.74	16.63	60.46	0.163		1.95
	163	0.296	0.06	2.251	-0.000	1.237	1.23	0.988	154.12	22.65	127.45	0.162		1.93
	290	004.0	0.06	2.180	-0.000	1.579	1.57	676.0	158.23	29.17	177.53	0.152		1.80
	515	0.410	0.06	2.169	-0.000	2.378	2.37	0.833	162.02	45.20	209.67	0.150		2.34

	A A I A O	DATA AT RESONANCE CONFIGURATION NO. 23	CE CONFI	GURATION	NO. 23									
D E	SONIC	>	۷IS	<b>.</b>	918	×	-	۵						
0.0790	1130.0	0.122	0.12200E-04	069.0	008000	009.0	0.100	0.056						
FREG	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLDK
1927.0	0.029	0.105	0.06	1.866	-0.000	0.514	0.51	0.897	137.58	8.99	54.55	0.167	0.40	1.71
1938.0		0.142	0.06	1.855	-0.000	0.673	0.67	0.962	143.45	12.61	74.01	0.165	0.39	1.72
1940.0		0.187	0.06	1.854	-0.000	906.0	06.0	0.997	149.59	17.95	97.67	0.165	04.0	1.82
1947.0		0.258	0.06	1.847	-0.000	1.165	1.16	766.0	154.35	23.79	135,31	0.163	0.37	1.72
1954.0		0.336	0.06	1.840	0000-0-	1.584	1.58	0.948	158.22	33.29	176.96	0.162	0.30	1.82
1951.0		7770	0.06	1.843	-0.000	2.141	2.14	0.868	162.30	45.99	232.93	0.163	0.39	1.89
1947.0		0.572	0.06	1.847	000-0-	2.961	2.06	0.754	166.50	64.75	2000	0.163	64.0	90.0

III, DATA FOR EVALUATION OF NEW DESIGN THEORY (SEE APPENDIX D

EXPERIMENTAL DATA FOR COMPARISON WITH DESIGN THEORY

DNLDK **K2RES** LEFF 455.09 862.09 1115.05.09 1115.05.05 1116.05.05 1116.05.05 1116.05 11 0.052 0.054 0.101 0.102 0.290 0.376 0.843 0.884 0.415 00.9926 00.9911 00.9930 00.993 0.0540 0.053 0.360 0.360 0.360 11.522 11.522 11.652 11.652 12.034 12.034 13.032 0.12200E-04 ۷IS 00.25 1130.0 645.0 835.0 1135.0 1135.0 11260.0 11561.0 11551.0 22000.0 21650.0 2756.0 2756.0 0.0750 DEN

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RESONATOR CONFIGURATION NO. 1

DEN SONIC	.0750 1129.0	FREG PA1	1572.0 0.016					
		P A 2	0.058	_	_	_	_	Ī
VIS	0.12200E-04	PHASF	92.0	88.7	87.6	87.2	87.5	86.8
A.	0.825	INERT	6.924	6.801	6.717	6.639	6.597	6.418
516	0.0140	REACT	990.0	-0.056	-0.140	-0.218	-0.260	-0.439
×	0.200	RESIS	1.909	2.489	3.356	4.473	5.967	7.862
-	0.100	IMPED	1.91	2.49	3.35	4.47	5.97	7.87
۵	0.052	ABSOR	0.901	0.817	0.706	0.596	0.491	300
	•	SPL	132.63	136.91	141.24	145.72	150.32	166.01
		DNLD	5.60	8.05	11.87	16.80	23,39	21.74
		UORF	47.23	64-42	84.92	113.24	151.02	2000
		LEFF	0.133	0.1.0	0000	0-127	0.126	
		KZRES	440	14.0	1410	24.0	0.42	
		DNLDK	1.14	9	200	1 2 2	1000	

RESONATOR CONFIGURATION NO. 2

	RESONATO	RESONATOR CONFIGURATION NO.3	SURATION	N • 0										
DEN	SONIC	۷IS	ý	٣	516	х	-	۵						
0.0750	1129.0	0.12200E-04	0E-04	0.831	0.0470	009•0	0.100	0.052						
FREG	PAl	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	K2RES	DNLOK
1540.0	0.029	660.0	53.9	1.932	10.401	0.550	0.0	0.858	137.22	5.32	70.18	•	2.	<u>,</u>
1540.0	0.036		- 0		4 4		• •	- 0	2000	•	9 -	71.	7 .	- 0
1540.0	0.000	0.118	6	. 90	0.42	68	•		40.0		. M	0.125	0.0	0.83
1540.0	0.045	.12	59.5	.89	.43	•72	•	.91	41.8	•	ં	.12	2	. eo
1540.0	0.051	. 13	60.8	O	44.	•79		•92	2.9	6	ë	.12	6	8
1540.0	0.057	0.143	62.2	1.895	0.43	•83	•	• 93	44.0	9.5	01.	.12	i.	æ
1540.0	0.064	• 15	63.8	0	• 42	• 8 7	•	• 94	45.1	0:1	60	.12	•2	æ
1540.0	0.072	• 16	64.9	O.	• 43	669	•	• 95	46.2	1.0	16.	• 12	7,	æ
1540.0	0.081	• 17	66.1	1.896	• 43	.98	•	• 95	47.3	1.8	24.	• 12	• 5	8
1540.0	0.091	0.187	67.3	O	44.	• 05	•	• 95	48.3	2.8	32.	.12		8
1540.0	0.102	0.198	68.5	1.889	44.	•12	•	• 95	49.3	3.9	0,	.12	7	æ
1540.0	0.115	0.210	69.7	Œ	77.	• 20	•	• 95	50.2	5.1	48.	. 12	• 2	6.
1540.0	0.129	0.225	40.0	89	.43	• 26	•	• 95	51.2	0.9	58.	.12	• 5	8
1540.0	0.145	•	72.0	98	77.	•36	•	• 94	52.1	7.5	•99	.12	6	6.
1540.0	0.163	• 24	72.9	89	0.44	• 45	•	• 93	53.0	8.9	76.	.12	6	3.
1540.0	0.182	97.	74.2	89	.43	• 55	•	• 92	53.9	0.3	86.	• 12	e.	•
1540.0	0.205	0.283	75.1	90	• 43	• 63	•	.91	54.8	1.5	900	.12		٥.
1540.0	0.230	• 29	76.1	89	• 43	• 75	•	• 90	55.6	3.4	60	.12		Ç.
1540.0	0.258	.31	77.2	91	• 45	• 8 4	•	• 89	56.5	4.7	24.	.12	6	6
1540.0	0.290	• 33	78.0	91	.41	96•	•	.87	57.3	6.5	37.	.12	6	6
1540.0	0.325	35	78.7	6	.41	.03	•	•86	58.2	8.3	51.	.12	6	6
1540.0	0.365		80.2	4	• 38	• 24	•	• 84	0.6	۲.	G	.12	6	•
1540.0	604.0	0.400	82.5	07	•31	• 36	•	. 82	59.9	2.5	82.	• 13	.3	6.

			DNLDK	1.33	1.47	1.42	1 • 4 2
			K2RES DI	0.50	44.0	0.40	0.39
			LEFF K	0.153	0.146	0.142	0.138
			UORF	27.10	72.94	114.28	169.04
			DNLD	3.28	11.77	18.21	27.57
			·SPL	134.95	145.84	151.24	156.47
	۵	0.052	ABSOR	0.378	0.622	902.0	0.748
	<b>-</b>	0.100	IMPED	1.18	1.00	1.57	1.89
	×k	0.500	RESIS	0.280	0.663	0.954	1.376
	516	0.0700	REACT	-1.150	-1.222	-1.257	-1.306
4 • 0N	Ą	0.784	INERT	1.593	1,571	1,485	1.436
URATION	S	0.12200E-04	PHASE	13.7	28.5	37.2	46.5
R CONFIG	\$1^	0.1220	PA2	0.067	1000	0.283	0.419
RESONATOR CONFIGURATION NO.4	SONIC	1129.0	PA1	0.029	100.0	0.163	0.290
	DEN	0.0750	FREG	1572.0	1572.0	1572.0	1572.0

	RESONATI	OR CONFI	RESONATOR CONFIGURATION NO.5	NO . 5										
DEN	SONIC	>	V I S	t	918	×	-	Δ						
0.0750	1129.0	0.122	0.12200E-04	0.780	0.0940	009•0	0.100	0.052		•				
FREG	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	KZRES	DNLDK
1572.0	0.029	0.059	4.6	1.194	-1.091	0.180	1.10	0.279	134.66	2.47	21.58	451.0	46.0	1.36
1572.0	0.040	0.083	11.7	1.189	-1.096	0.227	1:11	0.335	137.82	3.85	30.14	0.153	94.0	1.36
1572.0	0.051	0.102	13.6	1.172	-1.113	0.269	1.14	0.377	139.94	5.12	37.08	0.151	0.46	1.39
1572.0	790.0	0.129	16.2	1.185	-1.100	0.319	1.14	0.433	142.12	6.62	46.68	0.152	44.0	1.37
1572.0	0.091	0.174	20.7	1.163	-1.122	0.424	1.19	0.515	145.41	9.74	62.97	0.150	0.43	1.44
1572.0	0.129	0.230	26.6	1.136	-1.149	0.575	1.28	0.605	148.76	14.26	83.01	0.146	77.0	1.55
1572.0	0.163	0.73	28.4	1.089	-1.197	249.0	1.36	0.624	150.84	16.41	98.66	0.140	0.42	1.49
1572.0		0.365	27.2	1.142	-1.143	0.587	1.28	0.614	152.80	14.62	131.56	0.147	0.28	1.00
1572.0		0.481	34.5	1.150	-1.135	0.780	1.37	0.700	156.20	20.37	173.44	0.148	0.29	1.04
1572.0		0.627	43.9	1.210	-1.075	1.035	1.49	0.781	159.66	27.99	226.02	0.156	0.29	1.08

. THROUGH FLOW EXPERIMENTS

DATA WITH VARIABLE VELOCITY AT CONSTANT SOUND LEVEL 145 DB

VELTH	00.00	32.60	63.00	115.50	135.50	164.50	187.50	212.10	237.00	256.00	279.00	302.00	325.00
KZRES	0.44	19.0	1.39	3.22	5.53	8.43	11.98	16.22	20.95	25.85	31.85	41.10	46.17
LEFF	.0.111	0.105	0.093	0.082	0.076	0.072	0.072	0.070	0.071	0.075	0.077	0.081	0.088
UORF	88.06	70.76	48.95	32.34	24.82	20.17	16.97	14.61	12.87	11.60	10.46	9.22	• 10
DNLD	10.74	13,86	21.01	33.56	45.00	26.40	67.95	79.65	91.06	101.56	113.14	129.00	136.96
SPL	143.86	143.19	142.15	141.25	140.79	140.49	140.28	140.11	139.99	139.89	139.81	139.71	139.68
ABSOR	0.980	976.0	0.849	0.708	0.612	0.538	0.478	0.430	0.391	0.361	0.332	0.299	0.286
IMPED	1.17	1.46	2.11	3.19	4.16	5.12	6009	7.07	8.02	8.90	9.87	11.21	11.87
RESIS	1.143	1.408	2.015	3.080	4.050	5.018	5.998	6.991	7.959	8.850	9.833	11.179	11.854
REACT	-0.266	-0.390	-0.631	-0.854	-0.972	-1.039	-1.057	-1.082	-1.061	-0.992	976.0-	-0.860	-0.725
INERT	2.243	2.119	1.878	1.655	1.537	1.470	1.452	1.427	1.448	1.517	1.563	1.649	1.785
PHASE	76.9	74.5	72.6	74.5	76.5	78.3	80.0	81.2	82.4	83.6	84.5	85.6	86.5
PA2	0.110	0.088	0.061	0.040	0.031	0.025	0.021	0.018	0.016	0.014	0.013	0.011	0.010
PAI	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051
REO	750.0	750.0	750.0	750.0	750.0	1750.0	1750.0	1750.0	1750.0	1750.0	1750.0	1750.0	1750.0

0.052

060.0

0.500

CF 0.864

VIS 0.12200E-04

DEN 0.0720

SONIC 1150.0

S1G 0.0395

	DATA WIT	DATA WITH VARIARLE VELOCITY AT	LE VELOC		TONSTANT	CONSTANT SOUND LEVEL 16, DR	. 16. DB							
O N N	SONIC	>	۷IS	F.	SIG	×	-	۵						
0.0720	1150.0	0.1220	0.122UUE-U4	0.864	0.0395	) ) ()	6	0.052						
FREG	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	LEFF	K2RES	VELTH
1750.0			76.4	1.892	-0.618	2.554	2.62	0.784	156.69	27.37	221.21			000
1750.0	0.290	0.264	77.0	1.890	-0.619	2.681	2.75	0.769	156.59	28.87	211.25	0.093	0.43	32.60
1750.0			78.0	1,903	-0.606	2.851	2.91	0.750	156.47	30.87	199.43			63.00
1750.0			79.3	1.895	-0.614	3.251	9.30	0.704	156.23	35.58	175.71			115.50
1750.0			78.8	1.737	-0.772	3.902	3.97	0.633	155.88	43.25	146.15			135.50
1750.0			78.5	1.534	-0.975	4.796	4.89	0.555	155,56	53.78	118.79			164.50
1750.0			79.3	1.404	-1.105	5.848	5.95	0.486	155.30	66.19	97.68			187.50
1750.0			80.4	1.357	-1.152	6.816	6.91	0.436	155.13	77.59	84.10			212.10
1750.0			81.4	1.350	-1.159	7.669	7.75	004.0	155.02	87.65	74.95			237.00
1750.0			82.5	1.387	-1,123	8.530	8.60	0.370	154.92	97.19	67.57			256.00
1750.0			83.5	1.429	-1.080	9.481	9.54	0.341	154.83	109.00	60.92			279.00
1750.0			94.4	1.477	-1.032	10.534	10.58	0.314	154.75	121.41	54.93			302.00
1750.0			85.3	1.569	076-0-	11.434	11.47	0.294	154.70	132.02	50.67			325.00
														1

184.32 11584.32 11584.94 11585.94 1158.96 1159.96 1159.80 1159.80 1159.80 1159.80 1159.80 0.052 0.044m4mmm444m0 0.00000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.00000 0.000 060.0 0.500 **S16** 0.0395 INERT 0.864 266.3 465.1 665.1 700.0 700.0 700.0 866.0 900.8 1108.2 11120.4 11120.4 11120.4 0.12200E-04 0.290 0.290 0.290 0.290 0.290 0.290 0.290 0.290 0.290 0.290 0.290 1150.0 500.0 11500.0 11500.0 11700.0 11700.0 11800.0 22000.0 22000.0 22000.0 2400.0 3400.0 0.0720

DATA WITH VARIABLE FREQUENCY AT CONSTANT VELOCITY 136 ft/8ec

113866.000 113866.000 113866.000 113866.000 113866.000 113866.000 113866.000

# Pratt & Whitney Aircraft PWA FR-3299

DEN	SONIC	>	VIS	ñ	518	×	۳	٥						
0.0720	1150.0	0-122(	0.12200E-04	0.864	0.0395	0.500	0400	0.052						
FREG	PA1	PA2	PHASE	INERT	REACT	RES1S	IMPED	ABSOR	SP.	DNCD	CORF	LEFF	K2RES	VELTH
500.0	0.290	0.174	30.00	-2.625	-11.410	9,076	14.58	0.156	154.34	197.37	39.87	-0.455	7.71	237.0
10001	0.290	0.134	58.7	-0.542	-4.935	R-117	9.80	0.302	154.72	123.81	61.20	-0.047	64.4	237.0
1500.0	0.290	0.105	71.2	0.329	-2.599	7.635	8.06	0.375	154.94	94.45	72.08	0.019	3.59	237.0
1600.0	0.290	0.104	72.6	0.458	-2.287	7.299	7.64	0.393	154.99	87.22	76.01	0.024	3.25	237.0
1700.0	062.0	0.100	82.4	1,598	-0.985	7.386	7.45	0.414	155.06	85.58	78.02	0.081	3.21	237.0
1750.0	0.290	0.093	81.5	1.363	-1.146	7.671	7.75	0.401	155.02	87.67	74.95	0.067	3.47	237.0
1800.0	0.290	760.0	82.7	1.493	-0.947	7.397	7.45	0.414	155,06	83.19	77.99	0.071	3.21	237.0
1900.0	0.290	060.0	84.2	1.564	-0.747	7.357	7.39	0.417	155.07	80.48	78.61	0.071	3.17	237.0
2000-0	0.290	680.0	85.5	1.638	-0.557	7.085	7.10	0.431	155.11	75.37	84.60	0.071	2.93	237.0
2200.0	0.50	0.100	97.1	2.708	0.711	5,714	5.75	0.501	155.35	57.32	100.97	0.106	1.91	237.0
2500.0	0.290	0.067	97.2	2.707	0.950	7.522	7.58	604 0	155.04	71.43	76.68	6.093	3.32	237.0
2800.0	0.290	0.059	95.5	2,305	0.736	7.648	7.58	904.0	155.03	68.52	75.67	0.071	3.42	237.0
30000	0.290	0.059	100.2	2.734	1.269	7.058	7.17	0.424	155.09	60.79	81.07	0.079	2.55	237.0
3600.0	0.290	650.0	103.5	2.615	1.395	5.811	5.97	0.480	155.28	45.01	97.29	0.063	2.02	237.0
3900	0.290	0.045	108.5	3.381	2.254	6.739	7-10	0.414	155.06	50.46	81.81	0.075	2.79	237.0
425030	0.290	0.050	114.1	3.434	2.400	5.367	5.87	0.463	155,22	37.85	98.89	0.000	1.84	237.0

DATA WITH VARIABLE FREQUENCY AT CONSTANT VELOCITY 237 £t/800

# Pratt & Whitney Aircraft

DATA WITH VARIABLE FREQUENCY AT CONSTANT VELOCITY 302 ft/sec

PWA FR-3299

		VELTH	302.00	302.00	302.00	302.00	302-00	302.00	302.00	302.00	302.00	332.03	302.00	302.00	302°C0	302-00	302.vū	302-00
		KZRES	12.56	7.64	6.80	2.87	6-15	6.35	6.01	6.05	2.47	3.24	24.9	6.39	4.92	3.40	5.04	3.42
		LEFF				-0.002												
		UORF	33.16	47.50	52.82	56.35	56.52	55.56	57.15	56.95	59.95	77.48	54.91	55.45	62.93	75.52	61.35	74.15
		DNLD	268.13	168.60	132.13	119.69	119.88	119:99	115.09	112,33	103.90	75.14	100.61	94.16	79.57	59.65	69.32	53.87
		SPL	154.31	154.59	154.70	154.75	154.78	154.76	154.79	154.78	154.82	155.05	154.75	154.76	154.86	155.02	154.81	154.97
٥	0.052	ABSOR	0.147	0.254	0.295	0.312	0.322	0.317	0.325	0.324	0.338	0.410	0.312	0.317	7.349	.402	0,334	0.386
<b>+</b> =	060.0	IMPED	17.52	12.23	11,00	10.31	10.28	10.46	10.17	10.20	69.6	7.50	10.58	10.48	9.23	7.69	2.47	7.84
¥	0.500	RESIS	12,286	10.990	10.555	9.933	10.255	10.413	10.140	10.174	9.673	7.409	10.481	10.465	9.144	7.593	9.127	7.485
SIG	0.0395	REACT	-12.502	-5.384	-2.978	-2.792	-0.807	-1.021	-0.815	-0.836	-0.693	1.186	1.491	0.640	1.317	1.270	2.548	2.331
R	498.0	INERT	7117	991	640	-0.046	176	488	624	475	505	183	248	208	781	064	479	365
VIS	0-12200E-04	PHASE	44.5	63.9	74.3	74.3	25°	84.4	85.4	85.3	85 ° 9	99.1	1.86	93.5	98.2	99.5	105.6	107.3
>	0.122	PA2	0.145	0.104	0.077	0.077	0.072	690.0	697.0	0.065	0.065	0.077	0.048	0.043	0.045	0.045	0.034	0.038
SONIC	1150.0	PA1	0.290	0.290	0.290	0.290	0.290	0.290	0.290	0.290	0.290	0.290	0.290	0.50	0.290	0.240	0.290	0.290
DFR	0.0720	FREG	500.0	1000.0	1500.0	1600.0	1700.0	1750.0	1800.0	1900.0	200000	2200.0	2500.0	2800.0	30000	3600.0	390000	4250.0

			VELTH	00.0	2.00	38.00	15.50	31.70	98.00	00.62	147.00	00.65	18.00	00.90	3.00	11.00	258.00
			K2RES VE														14.90 25
			LEFF K2	0.185													0.181 1
			UORF LE														16.25 (
			DNCD														65.39
			SPL	142.37	142.29	142.76	143,30	144.25	144.16	143.77	143.33	143.04	142.79	142.62	142.36	142.26	142.08
	۵	0.052	ABSOR	0.875													0.840
. 145 DB	•	0.100	IMPED														2.32
CONSIANI SOUND LEVEL 145 DB	×	0.500	RESIS	624.0	0.466	0.551	0.660	0.934	1.155	1.314	1.512	1.661	1.802	1.910	2.094	2.169	2.325
S I WA I SN	516	0.1080	REACT	-0.031	670.0-	-0.083	-0.115	-0.159	-0.154	-0.156	-0.148	-0.124	-0.113	-0.100	-0.102	-0.075	690.0-
_	F.	0.916	INERT							1.712					1.766		
ב אברטכן	v	0E-04	PHASE	86.3	83.9	81.4	80.1	80.3	82.4	83.2	84.4	85.7	86.4	87.0	87.2	88.0	88.3
VAX1 ABL	V15	0.12200E-04	PA2	0.200	0.205	0.172	0.143	0.101	0.082	0.072	0.063	0.057	0.053	0.020	0.045	770.0	0.041
VALA WILL VARIABLE VELOCILY AL	SONIC	1150.0	PA1	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051	0.051
2	DEN	0.0720	FREG	2350.0	2350.0	2350.0	2350.0	2350.0	2350.0	2350.0	2350.0	2350.0	2350.0	2350.0	2350.0	2350.0	2350.0

	DATA WITH VARIABLE VELOCITY AT	H VARIABI	LE VELOC	ITY AT C	ONSTANT 5	CONSTANT SOUND LEVEL	. 160 DB							
DEN	SONIC	>	۷IS	£	516	×L	-	۵						
0.0720	1150.0	0.1220	0.12200F-04	0.916	0.1080	0.500	0.100	0.052						
FRFO	PA1	PA2	PHASE	INERT	REACT	RESIS	IMPED	ABSOR	SPL	DNLD	UORF	1 1 1 1	KZRES	VELTH
2350.0		0.546	85.4	1.789	-0.079	0.989	0.99	966.0	159.65	24.86	214.29	0.180	0.48	00.0
2350.0	0.290	0.527	6.40	1.776	-0.093	1.022	1.02	166.0	159.59	25.81	207.02	0.179	0.51	5.00
2350.0		0.527	0.40	1.761	-0.107	1.021	1.02	166.0	159.54	25.77	207.02	0.177	0.51	38.00
2350.0		0.515	83.8	1.755	-0.113	1.044	1.05	966.0	159.49	26.42	202.30	0.177	0.53	55.50
2350.0		0.503	83.5	1.747	-0.121	1.068	1.07	0.995	159.43	27.09	197.70	0.176	0.56	81.70
2350.0		6440	00 00 00	1.738	-0.130	1.199	1.20	0.988	159.10	30.77	176.20	0.175	0.10	108.00
2350.0		404.0	85.2	1.757	-0.112	1.333	1.33	0.977	158.78	34.54	158.86	0.177	0.87	129.00
2350.0		0.373	86.7	1.785	-0.083	1.448	1.45	0.965	158.51	37.76	146.55	0.180	1.03	147.00
2450.0		0.325	87.9	1.808	-0.061	1.664	1.66	0.937	158.05	43.84	127.64	0.182	1.35	169.00
2350.0		0.296	0.68	1.837	-0.031	1.826	1.82	0.914	157.77	48.37	116.41	0.185	1.63	186.00
2350.0		0.270	90.3	1.879	0.010	2.002	2.00	0.888	157.49	53.33	106.17	0.189	1.96	206.00
2350.0		0.252	91.0	1.906	0.037	2.145	2.14	0.867	157.30	57.35	80.66	0.192	2.25	223.00
2350.0		0.233	91.9	1.946	0.077	2.325	2.32	0.840	157.08	62.38	91.41	0.196	2.65	241.00
2350.0		0.222	92.2	1.962	0.093	2.434	2.43	0.824	156.96	65.44	87.30	0.198	2.90	258.00

VI. PAST FLOW EXPERIMENTS

DATA WITH VARIABLE VELOCITY AT CONSTANT SOUND LEVEL 150 DB

0.053

0.300

0.510

0.0212

0.670

0.12900E-04

SONIC 1151.0

518

0.00 1106.90 1126.90 1126.90 1126.90 1127.90 1127.90 1127.90 1128.90 1237.90 1250.10 1250.10 1250.10 1250.10 1250.10 00.200 00.200 00.200 00.201 00.201 00.200 00 

DATA WITH VARIARLE VELOCITY AT CONSTANT SOUND LEVEL 160 DB

0.00 1145.00 1155.00 1178.00 1178.00 1188.00 1188.00 1188.00 1189.00 1180.00 1 00.234 00.233 00.233 00.2333 00.2333 00.223 00.224 00.224 00.224 00.224 00.224 00.224 LEFF 647.50 647.50 6881 700.61 700.61 700.61 700.64 710.02 710.03 711.02 711.02 711.02 711.03 SPL 0.051 0.300 6.762 99.905 99.613 99.636 99.636 99.636 99.636 99.659 90.659 90.659 90.659 90.659 90. 25.226 2.320 2.320 2.320 2.3346 2.3346 2.3346 2.3366 2.3366 2.3366 2.366 516 0.0212 \$\times \times \ 0.670 0.13000E-04 V 1 S 0.122 0.108 0.108 0.105 0.105 0.105 0.105 0.105 0.105 0.105 0.105 0.105 0.105 0.105 1155.0 SONIC 0.0845 DEN

1 .		VELPT	9	5	05.2	•	39.3	53.2	66.0	77.2	87.5	97.0	06.5	14.2	22.0	29.4	36.5	43.1	40.4	55.5	51.8	57.3	72.5	77.5	82.4
	:	K2RES	7	4	.28	• 50	• 16	.11	100	0.0	.05	• 02	00.	90.	90.	-04	-01	.12	.12	• 18	27	.24	.29	32	1.36 2
	ļ.	LEFF	. 42	.33	.32		.31	• 29	.28	.27	.27	.26	• 25	.24	.23	• 23	.22	.21	.21	.21	.20	20	20	0.204	0.204
		UORF	~	ě	9	•	6	Ö	~	~	ω,	4	Š	ë	ຕໍ	ė	ë	ċ	٥,	-	ं	ċ	ċ		80
		DNLD	3.1	5.4	3.0	41.56	1.2	7.0	0.2	4 ° C	4.0	8.6	7.6	1.1	1.3	1.5	1.7	2.8	2.8	0	. 5	5.1	2	6.8	7.4
		SPL	44.9	45.3	45.4	45.	45.5	45.5	45.6	45.6	45.7	45.7	45.8	45.7	45.8	45.8	45.8	45.7	45.7	45.7	45.7	45.7	45.6	45.6	5.6
۵	660.0	ABSOR		7		0.527	*		•			9	9	Ψ	9	9	9	9	9	6		'n	S		
•-	0.300	IMPED	(1)	~	Œ	4.73	v	4	3	ิเก	2	~	~	~	4.21	2	2	3	S	J	4	5	9	4.67	۲.
×	0.510	RESIS	.41	•64	.32	4.190	.15	.11	0.	908	•00	•03	9	•14	.17	• 19	• 20	.30	.31	.41	•46	.51	.62	.67	.73
516	0.0272	REACT	• 0 6	77.	• 29	2.199	• 02	• 74	.57	.38	.21	• 05	.91	• 76	•62	•48	• 33	• 26	.21	.11	.03	00	8	8	•
£	0.670	INERT	-	6.295	.13	940.9	.87	• 59	• 41	• 23	• 05	6.00	• 76	.61	47	3	• 18		0.05	96.	• RB	.85	.83	3	. 83
V 1 S	0.12450E-04	PHASE	140.0	Ļ		117.7	•	9	÷	8	•	•	102.8	ċ	98.5	.9•96	9.46	93.5	92.8	91.5	90.5	90.1	89.9	89.9	89.9
<b>&gt;</b>	0.124	PA2	990.0	190.0	•01	0.074	0	7	0.80	S	ထိ	80	ဗိ	CB	0.083	80.	• 08	• 0B	⊕C•	•07	.07	60	.07	0.075	440.0
SONIC	1130.0	PA1	0.091	0.091	0.091	160.0	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091	0.091
DEN	0.0861	FREG	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0	1100.0

DATA WITH VARIABLE VELOCITY AT CONSTANT SOUND LEVEL 150 DB

			VELPT	0.0	3.8	27.7	38.7	52.1	64.2	175.20	85.2	6 • 46	39.2	11:1	18.4	25 • 5	32.2	38°	44.	50. 6	56.5	61.4	66.5	90.6
			K2RES	• 45	949	• 52	-57	.57	-57	0.58 1	5.00	• 58	• 59	• 59	• 59	• 59	• 59	9.	•61	.61	•61	• 61	• 61	. 61
			LEFF	0.371	•	•	•	•	•	0.310	•	•	•	•	•	•	•	•	•	•	•	•	•	•
			UORF	33.7	5.3	30.7	26.2	26.2	26.2	126.28	26.2	26.2	26.2	26.2	26.2	26.2	26.2	26.2	24.8	24.8	24.8	4.8	24.8	24.8
			DNLD	ı,	6.0	4.0	2.7	3.4	3.6	54.07	4.2	4.5	4.9	5.2	5.3	5.5	5.6	5.8	6.5	6.5	9•9	9.9	6.7	6•9
			SPL	55.1	55.2	55.3	55.2	55.2	55.2	155.30	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3	55.3
æ	۵	660.0	ABSOR	• 45	47	.48	47	• 48	.48	0.484	• 48	.48	640	640	640	640	649	• 49	640	49	640	640	649	•49
160 D	<b>-</b> -	0.300	IMPED		6	4	9	9	9	5.69	9	•	9	9	9	9	•	•	۲.					5.75
CONSTANT SOUND LEVEL	×k	0.510	RESIS	~	6.0	00	.21	.27	.30	5.340	.36	.38	.41	75.	46	47	.48	640	.56	5.7	.57	.58	5.8	5.608
CONSTANT	918	0.0272	REACT	11	64	. 26	.26	.12	90	6	90	.83	. 73	49.	59	5.5	.51	949	946	• 45	• 43	4.1	.38	1.294
<b>←</b>	F.	0.670	INERT																					5.141
SLE VELOC	· w	.12450E-C4	PHASE	125.5	119.9	114.3	113.5	111.9	111.3	110.2	109.6	108.8	107.8	106.8	106.3	105.9	105.4	104.9	104.7	104.6	104.4	104.2	103.9	103.0
DATA WITH VARIABLE VELOCITY A	SIA	0.1245	PA2	0.267	21	20	16	6	10	19	6	19	10	19	10	12	10	6	10	19	0	61	5	0.193
DATA WIT	SONIC	1130.0	PA1	0.000	0.200	0000	062.0	0.290	0.200	0.290	0.290	0.290	0.200	0.200	0.290	0.00	0.000	0.250	0.200	0.290	0.50	0.200	0.290	0.290
	DEN	0.0861	FREO	1100.0	0.0011	1100.0	1100.0	1100.0	1100-0	1100.0	1100.0	1100.0	0.0011	0.00[	1100	1100	1100	1100.0	110000	1100.0	1100.0	1100-0	0.0011	1100.0

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